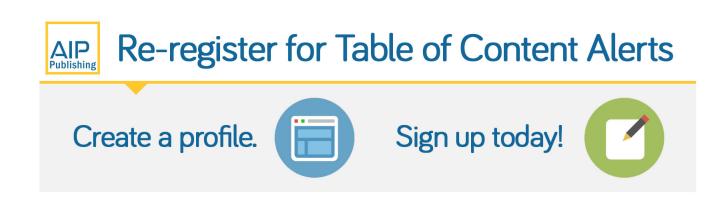


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On the absence of analytic integrability of the Bianchi Class B cosmological models

Antoni Ferragut,^{1,a)} Jaume Llibre,^{2,b)} and Chara Pantazi^{3,c)}

¹Departament de Matemàtica Aplicada I, Universitat Politècnica de Catalunya, ETSEIB, Av. Diagonal, 647, 08028 Barcelona, Catalonia, Spain

²Departament de Matemàtiques, Universitat Autònoma de Barcelona, Edifici C, 08193 Bellaterra, Barcelona, Catalonia, Spain

³Departament de Matemàtica Aplicada I, Universitat Politècnica de Catalunya, (EPSEB), Av. Doctor Marañón, 44–50, 08028 Barcelona, Spain

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We follow Bogoyavlensky's approach to deal with Bianchi class B cosmological models. We characterize the analytic integrability of such systems. © 2013 American Institute of Physics. [http://dx.doi.org/10.1063/1.4790828]

Bianchi models are cosmological models that describe space-times which are foliated by homogeneous hypersurfaces of constant time and are divided into two classes, Class A and Class B. There are many studies about the integrability of Class A. Here, we study the integrability of Class B. For the homogeneous cosmological models of Class B, Einstein's system of differential equations reduces to a dynamical system of dimension seven according to Bogoyavlensky's approach. We show that in order to study the integrability of such systems, it is sufficient to deal with homogeneous polynomial differential systems of dimension six. Concretely, Bianchi V is the simplest model and can be written as a homogeneous polynomial differential system of degree 2. Bianchi IV is dealt as a homogeneous polynomial differential system of degree 3 and the rest of the models, Bianchis III, VI, and VII are of degree 5. Due to the fact that all Bianchi class B models have been reduced to homogeneous polynomial differential systems, the study of their analytic integrability reduces to analyze their homogeneous polynomial first integrals. We show that Bianchi model V admits polynomial first integral, and we prove that the corresponding homogeneous polynomial differential systems that represent models Bianchi IV, III, VI, and VII do not admit polynomial first integrals. The fact that these Bianchi models are not completely integrable with analytic first integrals facilitates that they can have chaotic behavior.

I. INTRODUCTION AND STATEMENT OF THE RESULTS

Einstein's equations relate the geometry of the spacetime with the properties of the matter which occupied it. The matter occupying the space-time is determined by the stress energy tensor of the matter. In our study, we follow³ and we consider the hydrodynamical tensor of the matter. We will work with an equation of state of matter of the form $p = k\varepsilon$,

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where ε is the energy density of the matter, p is the pressure and $0 \le k < 1$.

We can found in the literature some methods in order to construct some Hamiltonians for the Bianchi class B models, see, for example, Ref. 4 and references therein. Here, we follow Bogoyavlensky's approach, see Ref. 3. So according to Bogoyavlensky, for the homogeneous cosmological models of Class B Einstein's system of equations reduces to the following dynamical system in the phase space $p_i, q_i, p_{\varphi}, \varphi$, i = 1, 2, 3,

$$\frac{dq_i}{d\tau} = \frac{\partial H}{\partial p_i}, \quad \frac{dp_i}{d\tau} = -\frac{\partial H}{\partial q_i} - h_i,$$

$$\frac{d\varphi}{d\tau} = \frac{\partial H}{\partial p_{\varphi}}, \quad \frac{dp_{\varphi}}{d\tau} = -\frac{\partial H}{\partial \varphi} - h_{\varphi},$$
(1)

where the function H is

$$H = \frac{1}{(q_1 q_2 q_3)^{\frac{1-k}{2}}} (T(p_i q_i) + V_G(q_i)),$$
(2)

with

$$T(p_i, q_i, p_{\varphi}) = 2 \sum_{1 \le i < j \le 3} p_i p_j q_i q_j - \sum_{i=1}^3 p_i^2 q_i^2 - \frac{p_{\varphi}^2 q_1 q_2}{(n_1 q_1 - n_2 q_2)^2}$$
$$V_G(q_i) = -\frac{1}{4} (12a^2 q_1 q_2 + (n_1 q_1 - n_2 q_2)^2),$$

and

$$h_{1} = \frac{a^{2}q_{2}}{(q_{1}q_{2}q_{3})^{\frac{1-k}{2}}}, \quad h_{2} = \frac{a^{2}q_{1}}{(q_{1}q_{2}q_{3})^{\frac{1-k}{2}}},$$
$$h_{3} = \frac{-2a^{2}q_{1}q_{2}}{q_{3}(q_{1}q_{2}q_{3})^{\frac{1-k}{2}}}, \quad h_{\varphi} = \frac{a(n_{1}q_{1} - n_{2}q_{2})^{2}}{(q_{1}q_{2}q_{3})^{\frac{1-k}{2}}}.$$

The constants $a \neq 0, n_1, n_2$ determine the type of model according to Table I, see also Refs. 1–3. System (1) in an explicit form writes as

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^{a)}Electronic mail: Antoni.Ferragut@upc.edu.

^{b)}Electronic mail: jllibre@mat.uab.cat.

^{c)}Electronic mail: chara.pantazi@upc.edu.

TABLE I. The classification of Bianchi class B cosmologies.

Туре	III	IV	V	VI	VII
a	1	1	1	$a \neq 1$	a
n_1	1	1	0	1	1
<i>n</i> ₂	-1	0	0	-1	1

$$\begin{aligned} \frac{dq_1}{d\tau} &= -2q_1(q_1q_2q_3)^{(k-1)/2}(p_1q_1 + p_2q_2 - p_3q_3),\\ \frac{dq_2}{d\tau} &= -2q_2(q_1q_2q_3)^{(k-1)/2}(p_1q_1 + p_3q_3 - p_2q_2),\\ \frac{dq_3}{d\tau} &= -2q_3(q_1q_2q_3)^{(k-1)/2}\left(p_1q_1 + p_2q_2 - p_3q_3),\\ \frac{dp_1}{d\tau} &= -(q_1q_2q_3)^{(k-1)/2}\left(2p_1(p_2q_2 + p_3q_3 - p_1q_1)\right) \\ &\quad + \frac{p_{\varphi}^2(n_1q_1 + n_2q_2)}{(n_1q_1 - n_2q_2)^3}q_2 - \frac{1}{2}n_1(n_1q_1 - n_2q_2) - 2a^2q_2\right) \\ &\quad + \frac{1-k}{2q_1}H \\ \frac{dp_2}{d\tau} &= -(q_1q_2q_3)^{(k-1)/2}\left(2p_2(p_1q_1 + p_3q_3 - p_2q_2)\right) \\ &\quad - \frac{p_{\varphi}^2(n_1q_1 + n_2q_2)}{(n_1q_1 - n_2q_2)^3}q_1 - \frac{1}{2}n_2(n_1q_1 - n_2q_2) - 2a^2q_1\right) \\ &\quad + \frac{1-k}{2q_2}H, \\ \frac{dp_3}{d\tau} &= -(q_1q_2q_3)^{(k-1)/2} \\ &\quad \times \left(2p_3(p_1q_1 + p_2q_2 - p_3q_3) - 2a^2\frac{q_1q_2}{q_3}\right) + \frac{1-k}{2q_3}H, \\ \frac{d\varphi}{d\tau} &= -(q_1q_2q_3)^{(k-1)/2}a(n_1q_1 - n_2q_2)^2, \end{aligned}$$
(3)

with $\overline{H} = T + V_G$.

System (1) applies in the subspace defined by Einstein's equation

$$R = p_1 q_1 + p_2 q_2 - 2p_3 q_3 + \frac{p_{\varphi}}{2a} = 0,$$
(4)

for more details see Ref. 3. Additionally, if \mathcal{X} is the associated vector field to system (3) we have that $\mathcal{X}(R) = 0$ and so R is a first integral of system (3). On the other hand, easy computations shows that

$$\mathcal{X}(H) = -4a^2 \frac{(q_1 q_2 q_3)^k}{q_3} R,$$

and so the function *H* given by Eq. (2) is a first integral of system (3) when this system is restricted to the hypersurface R = 0.

We notice that for Bianchi V we have $p_{\phi} = 0$ and $\dot{\phi} = 0$, so for this model we obtain a simplest model of six equations. After the change of coordinates and time

$$x_i = q_i, \quad x_{i+3} = p_i q_i, \quad i = 1, 2, 3, \quad d\tau_0 = \frac{(q_1 q_2 q_3)^{\frac{k-1}{2}}}{2} d\tau,$$

the Bianchi V model writes as a homogeneous polynomial differential system of degree 2:

$$\begin{aligned} \dot{x}_1 &= x_1(-x_4 + x_5 + x_6), \\ \dot{x}_2 &= x_2(x_4 - x_5 + x_6), \\ \dot{x}_3 &= x_3(x_4 + x_5 - x_6), \\ \dot{x}_4 &= x_1x_2 + \frac{k-1}{4}(3x_1x_2 + \Lambda), \\ \dot{x}_5 &= x_1x_2 + \frac{k-1}{4}(3x_1x_2 + \Lambda), \\ \dot{x}_6 &= x_1x_2 + \frac{k-1}{4}(3x_1x_2 + \Lambda), \end{aligned}$$
(5)

where

$$\Lambda = x_4^2 + x_5^2 + x_6^2 - 2(x_4x_5 + x_4x_6 + x_5x_6).$$
(6)

The condition stated in Eq. (4) reduces to $x_4 + x_5 - 2x_6 = 0$ for Bianchi V model. The function (2) becomes the first integral

$$(x_1x_2x_3)^{\frac{k-1}{2}}(3x_1x_2+\Lambda).$$

For Bianchi models III, IV, VI, and VII we notice that $n_1 = 1$. Moreover, system (3) is defined on the subspace (4), hence we can eliminate the momentum p_{φ} . So we can reduce the dimension of system (3) to seven. Note also that in order to study the integrability of system (3) we do not need to consider Eq. (7). In short, for studying the integrability of system (3), it is sufficient to deal with a differential system of dimension six.

For Bianchi IV after the change of coordinates and time

$$egin{aligned} &x_i = q_i, \quad x_{i+3} = p_i q_i, \quad i = 1, 2, 3, \ &d au_0 = rac{q_1 (q_1 q_2 q_3)^{rac{k-1}{2}}}{2} d au, \end{aligned}$$

and the above considerations we get the six-dimensional homogeneous polynomial differential system of degree 3

$$\begin{aligned} \dot{x}_1 &= x_1^2 (-x_4 + x_5 + x_6), \\ \dot{x}_2 &= x_1 x_2 (x_4 - x_5 + x_6), \\ \dot{x}_3 &= x_1 x_3 (x_4 + x_5 - x_6), \\ \dot{x}_4 &= \frac{x_1^3}{4} + x_1^2 x_2 - 2x_2 (x_4 + x_5 - 2x_6)^2 + \frac{k - 1}{4} R, \\ \dot{x}_5 &= x_1^2 x_2 + 2x_2 (x_4 + x_5 - 2x_6)^2 + \frac{k - 1}{4} R, \\ \dot{x}_6 &= x_1^2 x_2 + \frac{k - 1}{4} R, \end{aligned}$$
(7)

where

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$$R = x_1^3/4 + 3x_1^2x_2 + 4x_2(x_4 + x_5 - 2x_6)^2 + x_1\Lambda.$$

The function (2) becomes the first integral

$$(x_1x_2x_3)^{\frac{k-1}{2}}\left(\frac{x_1^2}{4} + 3x_1x_2 + \frac{4x_2(x_4 + x_5 - 2x_6)^2}{x_1} + \Lambda\right).$$

In the rest of the cases, i.e., for the Bianchi models III, VI, and VII after the change of coordinates and time

$$\begin{aligned} x_i &= q_i, \quad x_{i+3} = p_i q_i, \quad i = 1, 2, 3, \\ \frac{d\tau_0}{d\tau} &= \frac{N^3 (q_1 q_2 q_3)^{\frac{k-1}{2}}}{2}, \end{aligned}$$

where $N = x_1 - n_2 x_2$, and the above considerations we obtain the six-dimensional homogeneous polynomial differential system of degree 5

$$\begin{aligned} \dot{x}_{1} &= x_{1}N^{3}(-x_{4} + x_{5} + x_{6}), \\ \dot{x}_{2} &= x_{2}N^{3}(x_{4} - x_{5} + x_{6}), \\ \dot{x}_{3} &= x_{3}N^{3}(x_{4} + x_{5} - x_{6}), \\ \dot{x}_{4} &= \frac{1}{4}x_{1}N^{4} + a^{2}x_{1}x_{2}N^{3} + \frac{k-1}{4}NS \\ &- 2a^{2}x_{1}x_{2}(x_{1} + n_{2}x_{2})(x_{4} + x_{5} - 2x_{6})^{2}, \\ \dot{x}_{5} &= \frac{1}{4}N^{5} - \frac{1}{4}x_{1}N^{4} + a^{2}x_{1}x_{2}N^{3} + \frac{k-1}{4}NS \\ &+ 2a^{2}x_{1}x_{2}(x_{1} + n_{2}x_{2})(x_{4} + x_{5} - 2x_{6})^{2}, \\ \dot{x}_{6} &= a^{2}x_{1}x_{2}N^{3} + \frac{k-1}{4}NS, \end{aligned}$$

$$(8)$$

where

$$S = N^4/4 + 4a^2x_1x_2(x_4 + x_5 - 2x_6)^2 + N^2(3a^2x_1x_2 + \Lambda).$$

The function (2) becomes the first integral

$$(x_1x_2x_3)^{\frac{k-1}{2}}\left(\frac{N^2}{4} + 3a^2x_1x_2 + \Lambda + \frac{4a^2x_1x_2(x_4 + x_5 - 2x_6)^2}{N^2}\right).$$

A study of the integrability of Bianchi models using its symmetries has been done in Ref. 5, but no information is given there on the analytic integrability of these systems. The analytic integrability of Class A has been studied in previous works by several authors.^{5–10,12–17} Here, our aim is to study the analytic integrability of all Bianchi models of class B in the variables ($x_1, x_2, x_3, x_4, x_5, x_6$). In our study, we will use the following result, see Ref. 12.

Proposition 1. Let *F* be an analytic function and let $F = \sum_i F_i$ be its decomposition into homogeneous polynomials F_i of degree *i*. Then *F* is an analytic first integral of a homogeneous differential system if and only if for all i F_i is a homogeneous polynomial first integral of the homogeneous system.

Due to Proposition 1 and the fact that all Bianchi class B models have been reduced to homogeneous polynomial differential systems, see the systems (5), (7), and (8), the study of their analytic integrability reduces to analyze their homogeneous polynomial first integrals. Our main result is the following.

Theorem 2. The following statements hold

- (a) System (5) has the two independent first integrals $x_4 x_5$ and $x_4 x_6$. These two first integrals become the same when we restrict system (5) to (4), i.e. $x_4 + x_5 2x_6 = 0$, and any other polynomial first integral is a polynomial in the variable $x_4 x_5$.
- (b) System (7) has no polynomial first integrals.
- (c) Systems (8) have no polynomial first integrals.

Section II provides some technical lemmas that we will use for the proof of Theorem 2. In Sec. III, we prove the first statement of Theorem 2, namely, we study Bianchi V. In Sec. IV, we deal with Bianchi IV. The integrability of Bianchi III, VI, and VII is studied in Sec. V.

II. SOME AUXILIARY RESULTS

Lemma 3. Let x_k be a one-dimensional variable, $k \in \{1,...,n\}, n > 1$ and let $f = f(x_1,...,x_n)$ be a polynomial. For $l \in \{1,...,n\}$ and c_0 a constant let $f_l = f(x_1,...,x_n)|_{x_l=c_0}$. Then there exists a polynomial $g = g(x_1,...,x_n)$ such that $f = f_l + (x_l - c_0)g$ (see Ref. 11).

The next two lemmas are proved in Ref. 8.

Lemma 4. Let $g = g(x_4, x_5, x_6)$ be a homogeneous polynomial solution of the homogeneous partial differential equation

$$(a_1x_4 + a_2x_5 + a_3x_6)g + \frac{k-1}{4}\Lambda\left(\frac{\partial g}{\partial x_4} + \frac{\partial g}{\partial x_5} + \frac{\partial g}{\partial x_6}\right) = 0,$$
(9)

where $a_1, a_2, a_3 \in \mathbb{R}$ are such that $(a_1 - a_2)^2 + (a_1 - a_3)^2 \neq 0$. Then $g \equiv 0$.

Lemma 5. Let $g = g(x_4, x_5, x_6)$ and $h_2 = h_2(x_4 - x_5, x_4 - x_6)$ be homogeneous polynomials of respective degrees n - 2 and n such that

$$2(x_4 - x_5 + x_6)g + \frac{k-1}{4}\Lambda\left(\frac{\partial g}{\partial x_4} + \frac{\partial g}{\partial x_5} + \frac{\partial g}{\partial x_6}\right) + \frac{\partial h_2}{\partial x_5} = 0.$$
(10)

Then $h_2 = h_2(x_4 - x_6)$ *and* $g \equiv 0$.

III. PROOF OF STATEMENT (A) OF THEOREM 2

It is clear that system (5) has the first integrals $x_4 - x_5$ and $x_4 - x_6$. We shall prove in this section that under the restriction $x_4 + x_5 - 2x_6 = 0$ system (5) has only one independent first integral and it is $x_4 - x_5$.

Suppose that system (5) has a homogeneous polynomial first integral *h* of degree *n*. According to Lemma 3 we can write $h = h_1(x_2, x_3, x_4, x_5, x_6) + x_1^j g_1(x_1, x_2, x_3, x_4, x_5, x_6)$, with $x_1 \not\models g_1$ and $j \in \mathbb{N}$. Suppose that $g_1 \not\equiv 0$. System (5) on $x_1 = 0$ writes

$$\begin{aligned} \dot{x}_2 &= x_2(x_4 - x_5 + x_6), \\ \dot{x}_3 &= x_3(x_4 + x_5 - x_6) \\ \dot{x}_4 &= \frac{k - 1}{4}\Lambda, \\ \dot{x}_5 &= \frac{k - 1}{4}\Lambda, \\ \dot{x}_6 &= \frac{k - 1}{4}\Lambda. \end{aligned}$$
(11)

Since *h* is a first integral of system (5), we have that h_1 is a first integral of system (11). System (11) admits the two polynomial first integrals $x_4 - x_5$ and $x_4 - x_6$ and the two non-polynomial first integrals

$$x_{2}^{\frac{3}{2}(k-1)}\Lambda\left(\frac{x_{4}+x_{5}+x_{6}-2\sqrt{\Delta}}{x_{4}+x_{5}+x_{6}+2\sqrt{\Delta}}\right)^{\frac{x_{4}-2x_{5}+x_{6}}{\sqrt{\Delta}}}$$

and

$$x_{3}^{\frac{2}{2}(k-1)}\Lambda\left(\frac{x_{4}+x_{5}+x_{6}-2\sqrt{\Delta}}{x_{4}+x_{5}+x_{6}+2\sqrt{\Delta}}\right)^{\frac{x_{4}+x_{5}-2x_{6}}{\sqrt{\Delta}}},$$

where

$$\Delta = x_4^2 + x_5^2 + x_6^2 - x_4 x_5 - x_4 x_6 - x_5 x_6.$$
(12)

As these four first integrals of system (11) are independent and h_1 is a polynomial first integral of Eq. (11), we get, taking into account the equality $x_4 + x_5 - 2x_6 = 0$, that $h_1 = C_1(x_4 - x_5)^n$, where $C_1 \in \mathbb{R}$. Now since h and $x_4 - x_5$ are first integrals of system (5) we have that $x_1^j g_1$ is also a first integral of system (5). Therefore

$$j(-x_4 + x_5 + x_6)g_1 + x_1(-x_4 + x_5 + x_6)\frac{\partial g_1}{\partial x_1}$$
$$+ x_2(x_4 - x_5 + x_6)\frac{\partial g_1}{\partial x_2} + x_3(x_4 + x_5 - x_6)\frac{\partial g_1}{\partial x_3}$$
$$+ \left(x_1x_2 + \frac{k-1}{4}\Lambda\right)\left(\frac{\partial g_1}{\partial x_4} + \frac{\partial g_1}{\partial x_5} + \frac{\partial g_1}{\partial x_6}\right) = 0.$$

Let $\bar{g}_1 = g_1|_{x_1=0} \neq 0$. On $x_1 = 0$ we have

$$j(-x_4 + x_5 + x_6)\overline{g}_1 + x_2(x_4 - x_5 + x_6)\frac{\partial\overline{g}_1}{\partial x_2} + x_3(x_4 + x_5 - x_6)\frac{\partial\overline{g}_1}{\partial x_3} + \frac{k-1}{4}\Lambda\left(\frac{\partial\overline{g}_1}{\partial x_4} + \frac{\partial\overline{g}_1}{\partial x_5} + \frac{\partial\overline{g}_1}{\partial x_6}\right) = 0.$$

Write $\bar{g}_1 = x_2^l g_2$, with $l \in \mathbb{N} \cup \{0\}$, $x_2 \not\models g_2$ and $g_2 \not\equiv 0$. Then

$$\begin{aligned} \left[j(-x_4+x_5+x_6)+l(x_4-x_5+x_6)\right]g_2 \\ +x_2(x_4-x_5+x_6)\frac{\partial g_2}{\partial x_2}+x_3(x_4+x_5-x_6)\frac{\partial g_2}{\partial x_3} \\ +\frac{k-1}{4}\Lambda\left(\frac{\partial g_2}{\partial x_4}+\frac{\partial g_2}{\partial x_5}+\frac{\partial g_2}{\partial x_6}\right) &= 0. \end{aligned}$$

Set $\bar{g}_2 = g_2|_{x_2=0} \neq 0$. Then on $x_2 = 0$ we have

$$[j(-x_4+x_5+x_6)+l(x_4-x_5+x_6)]\bar{g}_2 + x_3(x_4+x_5-x_6)\frac{\partial\bar{g}_2}{\partial x_3} + \frac{k-1}{4}\Lambda\left(\frac{\partial\bar{g}_2}{\partial x_4} + \frac{\partial\bar{g}_2}{\partial x_5} + \frac{\partial\bar{g}_2}{\partial x_6}\right) = 0.$$

Now let $\bar{g}_2 = x_3^m g_3$, with $m \in \mathbb{N} \cup \{0\}$, $x_3 \not\downarrow g_3$ and $g_3 \not\equiv 0$. We have

$$\begin{aligned} [j(-x_4 + x_5 + x_6) + l(x_4 - x_5 + x_6) \\ + m(x_4 + x_5 - x_6)]g_3 + x_3(x_4 + x_5 - x_6)\frac{\partial g_3}{\partial x_3} \\ + \frac{k - 1}{4}\Lambda \left(\frac{\partial g_3}{\partial x_4} + \frac{\partial g_3}{\partial x_5} + \frac{\partial g_3}{\partial x_6}\right) &= 0. \end{aligned}$$

Let $\bar{g}_3 = g_3|_{x_3=0} \neq 0$. On $x_3 = 0$ we obtain

$$[j(-x_4+x_5+x_6)+l(x_4-x_5+x_6) +m(x_4+x_5-x_6)]\overline{g}_3+\frac{k-1}{4}\Lambda\left(\frac{\partial\overline{g}_3}{\partial x_4}+\frac{\partial\overline{g}_3}{\partial x_5}+\frac{\partial\overline{g}_3}{\partial x_6}\right)=0.$$

We are under the hypotheses of Lemma 4, hence, we have $\bar{g}_3 \equiv 0$, which is in contradiction with the assumptions. Therefore, $h = C_1(x_4 - x_5)^n$ and the proof follows.

IV. PROOF OF STATEMENT (B) OF THEOREM 2

We study in this section the analytic integrability of Bianchi model IV. We consider system (7). Let $h = h(x_1, ..., x_6)$ be a homogeneous polynomial first integral of degree *n* of system (7). Using Lemma 3 we can write $h = h_2(x_1, x_3, ..., x_6) + x_2^l g_2(x_1, ..., x_6)$, with $l \in \mathbb{N}$ and h_2 and g_2 homogeneous polynomials such that $x_2 \not\prec g_2$. Assume that $g_2 \not\equiv 0$. On $x_2 = 0$ system (7) becomes, after canceling a common factor x_1 , doing a change in the independent variable,

$$\dot{x}_{1} = x_{1}(-x_{4} + x_{5} + x_{6}),$$

$$\dot{x}_{3} = x_{3}(x_{4} + x_{5} - x_{6}),$$

$$\dot{x}_{4} = \frac{x_{1}^{2}}{4} + \frac{k - 1}{4} \left(\frac{x_{1}^{2}}{4} + \Lambda\right),$$

$$\dot{x}_{5} = \frac{k - 1}{4} \left(\frac{x_{1}^{2}}{4} + \Lambda\right),$$

$$\dot{x}_{6} = \frac{k - 1}{4} \left(\frac{x_{1}^{2}}{4} + \Lambda\right).$$
(13)

We notice that h_2 is a first integral of system (13). We write $h_2 = h_3(x_3, ..., x_6) + x_1^j g_3(x_1, x_3, ..., x_6)$, with $j \in \mathbb{N}$ and h_3 and g_3 homogeneous polynomials such that $x_1 \not \mid g_3$. Assume that $g_3 \not\equiv 0$. System (13) on $x_1 = 0$ writes

$$\dot{x}_{3} = x_{3}(x_{4} + x_{5} - x_{6}),$$

$$\dot{x}_{4} = \frac{k - 1}{4}\Lambda,$$

$$\dot{x}_{5} = \frac{k - 1}{4}\Lambda,$$

$$\dot{x}_{6} = \frac{k - 1}{4}\Lambda.$$

(14)

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Straightforward computations show that system (14) has the three independent first integrals $x_4 - x_5$, $x_4 - x_6$ and

$$x_{3}^{\frac{2}{2}(k-1)}\Lambda\left(\frac{x_{4}+x_{5}+x_{6}-2\sqrt{\Delta}}{x_{4}+x_{5}+x_{6}+2\sqrt{\Delta}}\right)^{\frac{x_{4}+x_{5}-2x}{\sqrt{\Delta}}}$$

where Δ is given by relation (12). As h_3 is a polynomial first integral of system (14), we have $h_3 = h_3(x_4 - x_5, x_5 - x_6)$. The following lemma shows that indeed $h = h_3(x_5 - x_6) + x_2^l g_2(x_1, \dots, x_6)$.

Lemma 6. We have that $h_3 = h_3(x_5 - x_6)$ and $g_3 \equiv 0$.

Proof. As $h_2 = h_3 + x_1^j g_3$ is a first integral of system (13), we have

$$x_{1}^{j} \left[j(-x_{4} + x_{5} + x_{6})g_{3} + x_{1}(-x_{4} + x_{5} + x_{6})\frac{\partial g_{3}}{\partial x_{1}} + x_{3}(x_{4} + x_{5} - x_{6})\frac{\partial g_{3}}{\partial x_{3}} + \frac{x_{1}^{2}}{4}\frac{\partial g_{3}}{\partial x_{4}} + \frac{k - 1}{4}\left(\frac{x_{1}^{2}}{4} + \Lambda\right)\left(\frac{\partial g_{3}}{\partial x_{4}} + \frac{\partial g_{3}}{\partial x_{5}} + \frac{\partial g_{3}}{\partial x_{6}}\right) \right] + \frac{x_{1}^{2}}{4}\frac{\partial h_{3}}{\partial x_{4}} = 0.$$
(15)

We distinguish some cases depending on the value of *j*.

If j = 1 then Eq. (15) becomes

$$(-x_4 + x_5 + x_6)g_3 + x_1(-x_4 + x_5 + x_6)\frac{\partial g_3}{\partial x_1}$$

+ $x_3(x_4 + x_5 - x_6)\frac{\partial g_3}{\partial x_3} + \frac{x_1^2}{4}\frac{\partial g_3}{\partial x_4}$
+ $\frac{k-1}{4}\left(\frac{x_1^2}{4} + \Lambda\right)\left(\frac{\partial g_3}{\partial x_4} + \frac{\partial g_3}{\partial x_5} + \frac{\partial g_3}{\partial x_6}\right) + \frac{x_1}{4}\frac{\partial h_3}{\partial x_4} = 0.$

Let $\bar{g}_3 = g_3|_{x_1=0} \neq 0$. On $x_1 = 0$ we have

$$(-x_4 + x_5 + x_6)\bar{g}_3 + x_3(x_4 + x_5 - x_6)\frac{\partial\bar{g}_3}{\partial x_3} + \frac{k-1}{4}\Lambda\left(\frac{\partial\bar{g}_3}{\partial x_4} + \frac{\partial\bar{g}_3}{\partial x_5} + \frac{\partial\bar{g}_3}{\partial x_6}\right) = 0.$$

Write $\bar{g}_3 = x_3^m g_4 \not\equiv 0$, with $m \in \mathbb{N} \cup \{0\}$ and $x_3 \not\models g_4$. Then,

$$[(-x_4 + x_5 + x_6) + m(x_4 + x_5 - x_6)]g_4$$

+ $x_3(x_4 + x_5 - x_6)\frac{\partial g_4}{\partial x_3} + \frac{k-1}{4}\Lambda\left(\frac{\partial g_4}{\partial x_4} + \frac{\partial g_4}{\partial x_5} + \frac{\partial g_4}{\partial x_6}\right) = 0.$

Let $\bar{g}_4 = g_4|_{x_3=0} \neq 0$. On $x_3 = 0$ we have

$$[(-x_4 + x_5 + x_6) + m(x_4 + x_5 - x_6)]\overline{g}_4 + \frac{k-1}{4}\Lambda\left(\frac{\partial \overline{g}_4}{\partial x_4} + \frac{\partial \overline{g}_4}{\partial x_5} + \frac{\partial \overline{g}_4}{\partial x_6}\right) = 0.$$

Applying Lemma 4 we obtain $\bar{g}_4 \equiv 0$, which is a contradiction. Hence $g_3 \equiv 0$. Back to Eq. (15) we have $\partial h_3 / \partial x_4 \equiv 0$, which means that $h_3 = h_3(x_5 - x_6)$. Then the lemma follows in the case j = 1.

If j > 2, then from Eq. (15) we have that $x_1 | (\partial h_3 / \partial x_4)$ and thus $\partial h_3 / \partial x_4 \equiv 0$. Now we can proceed as in the case j = 1 to obtain the equation

$$[j(-x_4 + x_5 + x_6) + m(x_4 + x_5 - x_6)]\bar{g}_4 + \frac{k-1}{4}\Lambda\left(\frac{\partial\bar{g}_4}{\partial x_4} + \frac{\partial\bar{g}_4}{\partial x_5} + \frac{\partial\bar{g}_4}{\partial x_6}\right) = 0.$$

Applying Lemma 4 we arrive to a contradiction and hence $g_3 \equiv 0$. The lemma follows in the case j > 2.

If j = 2 then Eq. (15) writes

$$2(-x_4 + x_5 + x_6)g_3 + x_1(-x_4 + x_5 + x_6)\frac{\partial g_3}{\partial x_1}$$
$$+ x_3(x_4 + x_5 - x_6)\frac{\partial g_3}{\partial x_3} + \frac{x_1^2}{4}\frac{\partial g_3}{\partial x_4}$$
$$+ \frac{k-1}{4}\left(\frac{x_1^2}{4} + \Lambda\right)\left(\frac{\partial g_3}{\partial x_4} + \frac{\partial g_3}{\partial x_5} + \frac{\partial g_3}{\partial x_6}\right) + \frac{1}{4}\frac{\partial h_3}{\partial x_4} = 0.$$

Let $\bar{g}_3 = g_3|_{x_1=0} \neq 0$. On $x_1 = 0$ we have

$$2(-x_4 + x_5 + x_6)\overline{g}_3 + x_3(x_4 + x_5 - x_6)\frac{\partial\overline{g}_3}{\partial x_3} + \frac{k-1}{4}\Lambda\left(\frac{\partial\overline{g}_3}{\partial x_4} + \frac{\partial\overline{g}_3}{\partial x_5} + \frac{\partial\overline{g}_3}{\partial x_6}\right) + \frac{1}{4}\frac{\partial h_3}{\partial x_4} = 0.$$

Write $\bar{g}_3 = x_3^m g_4 \neq 0$, with $m \in \mathbb{N} \cup \{0\}$ and $x_3 \not \mid g_4$. Then we get

$$x_{3}^{m} \left[[2(-x_{4} + x_{5} + x_{6}) + m(x_{4} + x_{5} - x_{6})]g_{4} + x_{3}(x_{4} + x_{5} - x_{6})\frac{\partial g_{4}}{\partial x_{3}} + \frac{k - 1}{4}\Lambda \left(\frac{\partial g_{4}}{\partial x_{4}} + \frac{\partial g_{4}}{\partial x_{5}} + \frac{\partial g_{4}}{\partial x_{6}}\right) \right] + \frac{1}{4}\frac{\partial h_{3}}{\partial x_{4}} = 0$$

If m > 0 then $x_3|(\partial h_3/\partial x_4)$. Hence $\partial h_3/\partial x_4 \equiv 0$ and $h_3 = h_3(x_5 - x_6)$. Let $\bar{g}_4 = g_4|_{x_3=0} \neq 0$. On $x_3 = 0$ we obtain

$$[2(-x_4+x_5+x_6)+m(x_4+x_5-x_6)]\bar{g}_4 + \frac{k-1}{4}\Lambda\left(\frac{\partial\bar{g}_4}{\partial x_4}+\frac{\partial\bar{g}_4}{\partial x_5}+\frac{\partial\bar{g}_4}{\partial x_6}\right) = 0.$$

Applying Lemma 4 we get a contradiction, hence we have $g_3 \equiv 0$.

In the case m=0, let $\bar{g}_4 = g_4|_{x_3=0} \neq 0$. On $x_3 = 0$ we obtain

$$2(-x_4 + x_5 + x_6)\bar{g}_4 + \frac{k-1}{4}\Lambda\left(\frac{\partial\bar{g}_4}{\partial x_4} + \frac{\partial\bar{g}_4}{\partial x_5} + \frac{\partial\bar{g}_4}{\partial x_6}\right) + \frac{1}{4}\frac{\partial h_3}{\partial x_4} = 0.$$

We can apply Lemma 5, permuting the variables x_4 by x_5 , and we get that $h_3 = h_3(x_5 - x_6)$ so $\partial h_3 / \partial x_4 \equiv 0$. Now applying Lemma 4 we obtain $\bar{g}_4 \equiv 0$. Hence the lemma follows in the case j = 2.

After Lemma 6 we have that $h = h_3(x_5 - x_6) + x_2^l g_2(x_1, ..., x_6)$, with $l \in \mathbb{N}$ and $x_2 \not\downarrow g_2$. We note that h_3 is

a homogeneous polynomial, hence, we can write $h_3(x_5 - x_6) = C_3(x_5 - x_6)^n$, with $C_3 \in \mathbb{R}$.

We recall that h is a first integral of system (7). Thus it satisfies the equation

$$\begin{aligned} x_{2}^{l} \left[lx_{1}(x_{4} - x_{5} + x_{6})g_{2} + x_{1}^{2}(-x_{4} + x_{5} + x_{6})\frac{\partial g_{2}}{\partial x_{1}} \\ &+ x_{1}x_{2}(x_{4} - x_{5} + x_{6})\frac{\partial g_{2}}{\partial x_{2}} + x_{1}x_{3}(x_{4} + x_{5} - x_{6})\frac{\partial g_{2}}{\partial x_{3}} \\ &+ \frac{k - 1}{4}R\left(\frac{\partial g_{2}}{\partial x_{4}} + \frac{\partial g_{2}}{\partial x_{5}} + \frac{\partial g_{2}}{\partial x_{6}}\right) \\ &+ \left(\frac{x_{1}^{3}}{4} + x_{1}^{2}x_{2} - 2x_{2}(x_{4} + x_{5} - 2x_{6})^{2}\right)\frac{\partial g_{2}}{\partial x_{4}} \\ &+ \left(x_{1}^{2}x_{2} + 2x_{2}(x_{4} + x_{5} - 2x_{6})^{2}\right)\frac{\partial g_{2}}{\partial x_{5}} + x_{1}^{2}x_{2}\frac{\partial g_{2}}{\partial x_{6}}\right] \\ &+ 2C_{3}nx_{2}(x_{4} + x_{5} - 2x_{6})^{2}(x_{5} - x_{6})^{n-1} = 0. \end{aligned}$$
(16)

The following lemma ends the proof of statement (b) of Theorem 2, as it shows that $h \equiv 0$.

Lemma 7. We have that $h_3 \equiv 0$ and $g_2 \equiv 0$.

Proof. Suppose that $g_2 \neq 0$. We distinguish two cases depending on the value of *l*. If l > 1 then from equation (16) we must take $C_3 = 0$ and therefore $h_3 \equiv 0$. Let $\bar{g}_2 = g_2|_{x_2=0} \neq 0$. After simplifying x_2^l , equation (16) on $x_2 = 0$ becomes, after cancelling a common factor x_1 ,

$$l(x_4 - x_5 + x_6)\overline{g}_2 + x_1(-x_4 + x_5 + x_6)\frac{\partial\overline{g}_2}{\partial x_1} + x_3(x_4 + x_5 - x_6)\frac{\partial\overline{g}_2}{\partial x_3} + \frac{x_1^2}{4}\frac{\partial\overline{g}_2}{\partial x_4} + \frac{k - 1}{4}\left(\frac{x_1^2}{4} + \Lambda\right)\left(\frac{\partial\overline{g}_2}{\partial x_4} + \frac{\partial\overline{g}_2}{\partial x_5} + \frac{\partial\overline{g}_2}{\partial x_6}\right) = 0.$$
(17)

Write $\bar{g}_2 = x_1^j g_3 \neq 0$, with $j \in \mathbb{N} \cup \{0\}$ and $x_1 \not\models g_3$. We get

$$\begin{aligned} |j(-x_4 + x_5 + x_6) + l(x_4 - x_5 + x_6)]g_3 \\ + x_1(-x_4 + x_5 + x_6)\frac{\partial g_3}{\partial x_1} + x_3(x_4 + x_5 - x_6)\frac{\partial g_3}{\partial x_3} + \frac{x_1^2}{4}\frac{\partial g_3}{\partial x_4} \\ + \frac{k - 1}{4}\left(\frac{x_1^2}{4} + \Lambda\right)\left(\frac{\partial g_3}{\partial x_4} + \frac{\partial g_3}{\partial x_5} + \frac{\partial g_3}{\partial x_6}\right) &= 0. \end{aligned}$$

Let $\bar{g}_3 = g_3|_{x_1=0} \neq 0$. Then, on $x_1 = 0$ we have

$$[j(-x_4 + x_5 + x_6) + l(x_4 - x_5 + x_6)]\bar{g}_3 + x_3(x_4 + x_5 - x_6)\frac{\partial\bar{g}_3}{\partial x_3} + \frac{k - 1}{4}\Lambda\left(\frac{\partial\bar{g}_3}{\partial x_4} + \frac{\partial\bar{g}_3}{\partial x_5} + \frac{\partial\bar{g}_3}{\partial x_6}\right) = 0.$$

Now write $\bar{g}_3 = x_3^m g_4 \neq 0$, with $m \in \mathbb{N} \cup \{0\}$ and $x_3 \not \mid g_4$. We get

$$\begin{aligned} [j(-x_4 + x_5 + x_6) + l(x_4 - x_5 + x_6) \\ &+ m(x_4 + x_5 - x_6)]g_4 + x_3(x_4 + x_5 - x_6)\frac{\partial g_4}{\partial x_3} \\ &+ \frac{k - 1}{4}\Lambda\left(\frac{\partial g_4}{\partial x_4} + \frac{\partial g_4}{\partial x_5} + \frac{\partial g_4}{\partial x_6}\right) = 0. \end{aligned}$$

Let $\bar{g}_4 = g_4|_{x_3=0} \neq 0$. Then, on $x_3 = 0$ we have

$$[j(-x_4+x_5+x_6)+l(x_4-x_5+x_6)+m(x_4+x_5-x_6)]\overline{g}_4$$
$$+\frac{k-1}{4}\Lambda\left(\frac{\partial\overline{g}_4}{\partial x_4}+\frac{\partial\overline{g}_4}{\partial x_5}+\frac{\partial\overline{g}_4}{\partial x_6}\right)=0.$$

Applying Lemma 4 we obtain $\bar{g}_4 \equiv 0$, a contradiction. Hence $g_2 \equiv 0$ and the lemma follows in the case l > 1.

If l=1 then we can cancel a common factor x_2 in Eq. (16). Let $\bar{g}_2 = g_2|_{x_2=0} \neq 0$. On $x_2 = 0$ Eq. (16) becomes

$$x_{1} \left[(x_{4} - x_{5} + x_{6})\bar{g}_{2} + x_{1}(-x_{4} + x_{5} + x_{6})\frac{\partial\bar{g}_{2}}{\partial x_{1}} + x_{3}(x_{4} + x_{5} - x_{6})\frac{\partial\bar{g}_{2}}{\partial x_{3}} + \frac{x_{1}^{2}}{4}\frac{\partial\bar{g}_{2}}{\partial x_{4}} + \frac{k - 1}{4}\left(\frac{x_{1}^{2}}{4} + \Lambda\right)\left(\frac{\partial\bar{g}_{2}}{\partial x_{4}} + \frac{\partial\bar{g}_{2}}{\partial x_{5}} + \frac{\partial\bar{g}_{2}}{\partial x_{6}}\right) \right] + 2C_{3}n(x_{4} + x_{5} - 2x_{6})^{2}(x_{5} - x_{6})^{n-1} = 0.$$

Clearly we must take $C_3 = 0$, and hence $h_3 \equiv 0$. Then the equation writes

$$(x_4 - x_5 + x_6)\overline{g}_2 + x_1(-x_4 + x_5 + x_6)\frac{\partial g_2}{\partial x_1} + x_3(x_4 + x_5 - x_6)\frac{\partial \overline{g}_2}{\partial x_3} + \frac{x_1^2}{4}\frac{\partial \overline{g}_2}{\partial x_4} + \frac{k - 1}{4}\left(\frac{x_1^2}{4} + \Lambda\right)\left(\frac{\partial \overline{g}_2}{\partial x_4} + \frac{\partial \overline{g}_2}{\partial x_5} + \frac{\partial \overline{g}_2}{\partial x_6}\right) = 0.$$
(18)

Write now $\bar{g}_2 = x_1^j g_3 \neq 0$, with $j \in \mathbb{N} \cup \{0\}$ and $x_1 \not > g_3$. Then the above equation becomes

$$[j(-x_4 + x_5 + x_6) + (x_4 - x_5 + x_6)]g_3 + x_1(-x_4 + x_5 + x_6)\frac{\partial g_3}{\partial x_1} + \frac{x_1^2}{4}\frac{\partial g_3}{\partial x_4} + x_3(x_4 + x_5 - x_6)\frac{\partial g_3}{\partial x_3} + \frac{k - 1}{4}\left(\frac{x_1^2}{4} + \Lambda\right)\left(\frac{\partial g_3}{\partial x_4} + \frac{\partial g_3}{\partial x_5} + \frac{\partial g_3}{\partial x_6}\right) = 0.$$
(19)

Let $\overline{g}_3 = g_3|_{x_1=0} \neq 0$. Then, on $x_1 = 0$ we have

$$[j(-x_4+x_5+x_6)+(x_4-x_5+x_6)]\overline{g}_3 + x_3(x_4+x_5-x_6)\frac{\partial\overline{g}_3}{\partial x_3} + \frac{k-1}{4}\Lambda\left(\frac{\partial\overline{g}_3}{\partial x_4} + \frac{\partial\overline{g}_3}{\partial x_5} + \frac{\partial\overline{g}_3}{\partial x_6}\right) = 0.$$

Now write $\bar{g}_3 = x_3^m g_4 \neq 0$, with $m \in \mathbb{N} \cup \{0\}$ and $x_3 \neq g_4$. We get

$$[j(-x_4 + x_5 + x_6) + (x_4 - x_5 + x_6) + m(x_4 + x_5 - x_6)]g_4 + x_3(x_4 + x_5 - x_6)\frac{\partial g_4}{\partial x_3} + \frac{k - 1}{4}\Lambda \left(\frac{\partial g_4}{\partial x_4} + \frac{\partial g_4}{\partial x_5} + \frac{\partial g_4}{\partial x_6}\right) = 0.$$

Let $\bar{g}_4 = g_4|_{x_3=0} \not\equiv 0$. Then, on $x_3 = 0$ we have

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$$[j(-x_4 + x_5 + x_6) + (x_4 - x_5 + x_6) + m(x_4 + x_5 - x_6)]\bar{g}_4 + \frac{k - 1}{4}\Lambda\left(\frac{\partial \bar{g}_4}{\partial x_4} + \frac{\partial \bar{g}_4}{\partial x_5} + \frac{\partial \bar{g}_4}{\partial x_6}\right) = 0$$

Applying Lemma 4 we obtain $\bar{g}_4 \equiv 0$, a contradiction. Hence $g_2 \equiv 0$ and the lemma follows also in the case l = 1.

We have proved that the first integral h is identically zero. Therefore, the system cannot have a polynomial first integral. Statement (b) of Theorem 2 follows.

V. PROOF OF STATEMENT (C) OF THEOREM 2

We study in this section the analytic integrability of Bianchi models III, VI, and VII.

Consider system (8) and let $h = h(x_1, ..., x_6)$ be a homogeneous polynomial first integral of degree *n* of this system. Applying Lemma 3 we can write $h = h_1(x_2, ..., x_6)$ $+ x_1^j g_1(x_1, ..., x_6)$, with $j \in \mathbb{N}$ and h_1 and g_1 homogeneous polynomials such that $x_1 \neq g_1$.

Assume that $g_1 \neq 0$. On $x_1 = 0$ system (8) becomes, after canceling a common factor $-n_2 x_2^3$,

$$\begin{aligned} \dot{x}_2 &= x_2(x_4 - x_5 + x_6), \\ \dot{x}_3 &= x_3(x_4 + x_5 - x_6), \\ \dot{x}_4 &= \frac{k - 1}{4} \left(\frac{x_2^2}{4} + \Lambda \right), \\ \dot{x}_5 &= \frac{x_2^2}{4} + \frac{k - 1}{4} \left(\frac{x_2^2}{4} + \Lambda \right), \\ \dot{x}_6 &= \frac{k - 1}{4} \left(\frac{x_2^2}{4} + \Lambda \right). \end{aligned}$$
(20)

We note that h_1 is a first integral of system (20). The following lemma provides more information about the expression of h_1 .

Lemma 8. We have $h_1 = h_1(x_4 - x_6)$.

Proof. Swapping x_1 and x_2 and swapping x_4 and x_5 system (20) is system (13), for which we have proved that there is no other polynomial first integral than 0, see Lemma 6. Then the lemma follows.

After Lemma 8 we have that $h = h_1(x_4 - x_6) + x_1^j g_1(x_1, ..., x_6)$, with $j \in \mathbb{N}$ and $x_1 \not\downarrow g_1$. We recall that h is a first integral of system (8). Thus it satisfies the equation

$$x_{1}^{j} \left[jN^{3}(-x_{4}+x_{5}+x_{6})g_{1}+x_{1}N^{3}(-x_{4}+x_{5}+x_{6})\frac{\partial g_{1}}{\partial x_{1}}+x_{2}N^{3}(x_{4}-x_{5}+x_{6})\frac{\partial g_{1}}{\partial x_{2}}+x_{3}N^{3}(x_{4}+x_{5}-x_{6})\frac{\partial g_{1}}{\partial x_{3}}\right. \\ \left. +\frac{k-1}{4}NS\left(\frac{\partial g_{1}}{\partial x_{4}}+\frac{\partial g_{1}}{\partial x_{5}}+\frac{\partial g_{1}}{\partial x_{6}}\right)+\left(\frac{1}{4}x_{1}N^{4}+a^{2}x_{1}x_{2}N^{3}-2a^{2}x_{1}x_{2}(x_{1}+n_{2}x_{2})(x_{4}+x_{5}-2x_{6})^{2}\right)\frac{\partial g_{1}}{\partial x_{4}}\right. \\ \left. +\left(\frac{1}{4}N^{5}-\frac{1}{4}x_{1}N^{4}+a^{2}x_{1}x_{2}N^{3}+2a^{2}x_{1}x_{2}(x_{1}+n_{2}x_{2})(x_{4}+x_{5}-2x_{6})^{2}\right)\frac{\partial g_{1}}{\partial x_{5}}+a^{2}x_{1}x_{2}N^{3}\frac{\partial g_{1}}{\partial x_{6}}\right] +a^{2}x_{1}x_{2}N^{3}\frac{\partial h_{1}}{\partial x_{6}} \\ \left. +\left(\frac{1}{4}x_{1}N^{4}+a^{2}x_{1}x_{2}N^{3}-2a^{2}x_{1}x_{2}(x_{1}+n_{2}x_{2})(x_{4}+x_{5}-2x_{6})^{2}\right)\frac{\partial h_{1}}{\partial x_{4}}=0.$$

$$(21)$$

The following lemma ends the proof of statement (c) of Theorem 2, as it shows that $h \equiv 0$.

Lemma 9. We have that $h_1 \equiv 0$ and $g_1 \equiv 0$.

Proof. Write $h_1(x_4 - x_6) = C_1(x_4 - x_6)^n$, with $C_1 \in \mathbb{R}$. Suppose that $g_1 \neq 0$. We distinguish two cases depending on the value of *j*. If j > 1 then from Eq. (21) we have that x_1 divides

$$C_1 n \left(\frac{x_2^4}{4} - 2a^2 n_2 x_2^2 (x_4 + x_5 - 2x_6)^2 \right).$$

Hence, we must take $C_2 = 0$ and therefore $h_2 \equiv 0$. Let $\bar{g}_1 = g_1|_{x_1=0} \neq 0$. Equation (21) on $x_1 = 0$ becomes, after cancelling a common factor $-n_2 x_2^3$,

$$j(-x_4 + x_5 + x_6)\overline{g}_1 + x_2(x_4 - x_5 + x_6)\frac{\partial\overline{g}_1}{\partial x_2} + x_3(x_4 + x_5 - x_6)\frac{\partial\overline{g}_1}{\partial x_3} + \frac{x_2^2}{4}\frac{\partial\overline{g}_1}{\partial x_5} + \frac{k-1}{4}\left(\frac{x_2^2}{4} + \Lambda\right)\left(\frac{\partial\overline{g}_1}{\partial x_4} + \frac{\partial\overline{g}_1}{\partial x_5} + \frac{\partial\overline{g}_1}{\partial x_6}\right) = 0.$$

Swapping x_1 and x_2 and swapping x_4 and x_5 we obtain Eq. (17). Hence we have $g_1 \equiv 0$ and the lemma follows in the case j > 1.

If j = 1 then we can cancel a common factor x_1 in equation (21). Let $\bar{g}_1 = g_1|_{x_1=0} \neq 0$. On $x_1 = 0$ Eq. (21) becomes, after cancelling a common factor $-n_2 x_2^2$,

$$\begin{aligned} x_2 \bigg[(-x_4 + x_5 + x_6) \bar{g}_1 + x_2 (x_4 - x_5 + x_6) \frac{\partial \bar{g}_1}{\partial x_2} \\ &+ x_3 (x_4 + x_5 - x_6) \frac{\partial \bar{g}_1}{\partial x_3} + \frac{x_2^2}{4} \frac{\partial \bar{g}_1}{\partial x_5} \\ &+ \frac{k - 1}{4} \left(\frac{x_2^2}{4} + \Lambda \right) \left(\frac{\partial \bar{g}_1}{\partial x_4} + \frac{\partial \bar{g}_1}{\partial x_5} + \frac{\partial \bar{g}_1}{\partial x_6} \right) \bigg] \\ &+ C_1 n \Big(2a^2 (x_4 + x_5 - 2x_6)^2 - \frac{n_2}{4} x_2^2 \Big) (x_4 - x_6)^{n-1} = 0. \end{aligned}$$

Clearly we must take $C_1 = 0$, and hence $h_1 \equiv 0$. Once again swapping x_1 and x_2 and swapping x_4 and x_5 this equation is Eq. (18). Hence, we have $g_1 \equiv 0$ and the lemma follows in the case j = 1.

VI. DISCUSSION

In this work we have proved that the Bianchi model V of Class B is partially integrable with analytic first integrals, but not completely integrable, and that the Bianchi models III, IV, VI, and VII of Class B have no analytic first integrals. Consequently, the partial integrability of the model V and the non-analytic integrability of the other Bianchi models of class B facilitates that they can have chaotic behavior.

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