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Some Notes to Extend the Study on Random Non-Autonomous Second Order Linear Differential Equations Appearing in Mathematical Modeling

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Abstract: The objective of this paper is to complete certain issues from our recent contribution (Calatayud, J.; Cortés, J.-C.; Jornet, M.; Villafuerte, L. Random non-autonomous second order linear differential equations: mean square analytic solutions and their statistical properties. *Adv. Differ. Equ.* 2018, 392, 1–29, doi:10.1186/s13662-018-1848-8). We restate the main theorem therein that deals with the homogeneous case, so that the hypotheses are clearer and also easier to check in applications. Another novelty is that we tackle the non-homogeneous equation with a theorem of existence of mean square analytic solution and a numerical example. We also prove the uniqueness of mean square solution via a habitual Lipschitz condition that extends the classical Picard theorem to mean square calculus. In this manner, the study on general random non-autonomous second order linear differential equations with analytic data processes is completely resolved. Finally, we relate our exposition based on random power series with polynomial chaos expansions and the random differential transform method, the latter being a reformulation of our random Fröbenius method.

Keywords: random non-autonomous second order linear differential equation; mean square analytic solution; random power series; uncertainty quantification

MSC: 34F05; 60H10; 60H35; 65C20; 65C30

1. Introduction

The important role played by differential equations in dealing with mathematical modeling is beyond discussion. They are powerful tools to describe the dynamics of phenomena appearing in a variety of distinct realms, such as engineering, biomedicine, chemistry, social behavior, etc. [1–3]. In this paper, we concentrate on a class of differential equations that have played a distinguished role in a variety of applications in science, in particular in physics and engineering, namely second order linear differential equations. Indeed, these equations have been successfully applied to describe, for example, vibrations in springs (free undamped or simple harmonic motion, damped vibrations subject to a frictional force, or forced vibrations affected by an external force), the analysis of electric circuits made up of an electromotive force supplied by a battery or a generator, a resistor, an inductor, and a capacitor. In the former type of problems, second order linear differential equations are formulated by applying Newton's second law, while in the latter case, this class of equations appears via the application of Kirchhoff's voltage law. In these examples, the formulation of second order linear differential equations to describe the aforementioned physical problems appears as direct applications of important laws of physics. However, this class of equations also arises indirectly when solving significant partial differential equations in physics. In this regard, Airy, Hermite, Laguerre, Legendre,

or Bessel differential equations are non-autonomous second order linear differential equations that emerge in this way. For example, the Airy equation appears when solving Schrödinger's equation with triangular potential and for a particle subject to a one-dimensional constant force field [4]; the Hermite equation emerges in dealing with the analysis of Schrödinger's equation for a harmonic oscillator in quantum mechanics [5]; the Laguerre equation plays a main role in quantum mechanics for the study of the hydrogen atom via Schrödinger's equation using radial functions [6] (Ch. 10); the Legendre equation appears when solving the Laplace equation to compute the potential of a conservative field such as the space gravitational potential using spherical coordinates [7]; and finally, the Bessel equation is encountered, for example, when solving the Helmholtz equation in cylindrical or spherical coordinates by using the method of the separation of variables [6] (Ch. 9).

In all the previous examples, two important features can be highlighted to motivate our subsequent analysis. First, the coefficients of the differential equations are analytic (specifically polynomials). Second, these coefficients depend on physical parameters that, in practice, need to be fixed after measurements; therefore, they involve uncertainty. Both facts motivate the study of random non-autonomous second order linear differential equations, whose coefficients and initial conditions are analytic stochastic processes and random initial conditions, respectively. The aim of our contribution is to advance the analysis (both theoretical and practical) of this important class of equations. In our subsequent development, we mainly focus on the theoretical aspects of such an analysis with the conviction that it can become really useful in future applications where randomness is considered in that class of differential equations. In this sense, some numerical experiments illustrating and demonstrating the potentiality of our main findings are also included. The study of random non-autonomous second order linear differential equations has been carried out for particular cases, such as Airy, Hermite, Legendre, Laguerre, and Bessel equations (see [8–13], respectively), and the general case [14–17]. Alternative approaches to study this class of random/stochastic differential equations include the so-called probabilistic transformation method [18] and stochastic numerical schemes [19,20], for example.

For the sake of clarity in the presentation, the layout of the paper is as follows: In Section 2, we study the homogeneous random non-autonomous second order linear differential. The analysis includes a result (Theorem 2) that simplifies the application of a recent finding by the authors that is particularly useful in practical cases. This issue is illustrated via several numerical examples where both the random Airy and Hermite differential equations are treated. In Section 3, the analysis is extended to a random non-autonomous second order linear differential equation with a forcing term. In this study, we have included conditions under which the solution is unique in the mean square sense. This theoretical study is supported with a numerical example as well. Section 4 is addressed to enrich our contribution by comparing the random Fröbenius method proposed in this paper against other alternative approaches widely used in the extant literature, specifically generalized polynomial chaos (gPC) expansions, Monte Carlo simulations, and the random differential transform method. Conclusions and future research lines are drawn in Section 5.

2. Homogeneous Case

We consider the general form of a homogeneous random non-autonomous second order linear differential equation in an underlying complete probability space $(\Omega, \mathcal{F}, \mathbb{P})$:

$$\begin{cases} \ddot{X}(t) + A(t)\dot{X}(t) + B(t)X(t) = 0, \ t \in \mathbb{R}, \\ X(t_0) = Y_0, \\ \dot{X}(t_0) = Y_1. \end{cases}$$
 (1)

It is assumed that the stochastic processes A(t) and B(t) are analytic at t_0 in the mean square sense [21] (p. 99):

$$A(t) = \sum_{n=0}^{\infty} A_n (t - t_0)^n$$
, $B(t) = \sum_{n=0}^{\infty} B_n (t - t_0)^n$, $t \in (t_0 - r, r_0 + r)$,

with convergence in $L^2(\Omega)$. The terms A_0, A_1, \ldots and B_0, B_1, \ldots are random variables. In fact, they are related to A(t) and B(t), respectively, via Taylor expansions:

$$A_n = \frac{A^{(n)}(t_0)}{n!}, \quad B_n = \frac{B^{(n)}(t_0)}{n!},$$

where the derivatives are considered in the mean square sense. According to the Fröbenius method, we look for a solution stochastic process X(t) also expressible as a mean square convergent random power series on $(t_0 - r, t_0 + r)$:

$$X(t) = \sum_{n=0}^{\infty} X_n (t - t_0)^n.$$

mean square convergence is important, as it allows approximating the expectation (average) and variance (dispersion) statistics of X(t) at each t [21] (Th. 4.2.1, Th. 4.3.1). This is one of the primary goals of uncertainty quantification [22].

Proposition 1 ([21] (Th. 4.2.1, Th. 4.3.1)). Let $\{Z_n\}_{n=1}^{\infty}$ and Z be second order random variables. If Z_n converges to Z as $n \to \infty$ in $L^2(\Omega)$ (i.e., in the mean square sense), then the expectation and variance of Z can be approximated as follows:

$$\mathbb{E}[Z(t)] = \lim_{n \to \infty} \mathbb{E}[Z_n(t)], \quad \mathbb{V}[Z(t)] = \lim_{n \to \infty} \mathbb{V}[Z_n(t)].$$

In [17], some auxiliary theorems on random power series were stated and proven: differentiation of random power series in the $L^p(\Omega)$ sense [17] (Th. 3.1) and Mertens' theorem for random series in the mean square sense [17] (Th. 3.2), which generalize their deterministic counterparts.

Proposition 2 (Differentiation of a random power series in the $L^p(\Omega)$ sense [17] (Th. 3.1)). Let $A(t) = \sum_{n=0}^{\infty} A_n(t-t_0)^n$ be a random power series in the $L^p(\Omega)$ setting $(p \ge 1)$, for $t \in (t_0-r,t_0+r)$, r > 0. Then, the random power series $\sum_{n=1}^{\infty} nA_n(t-t_0)^{n-1}$ exists in $L^p(\Omega)$ for $t \in (t_0-r,t_0+r)$, and moreover, the $L^p(\Omega)$ derivative of A(t) is equal to it: $\dot{A}(t) = \sum_{n=1}^{\infty} nA_n(t-t_0)^{n-1}$, for all $t \in (t_0-r,t_0+r)$.

Proposition 3 (Mertens' theorem for random series in the mean square sense [17] (Th. 3.2)). Let $U = \sum_{n=0}^{\infty} U_n$ and $V = \sum_{n=0}^{\infty} V_n$ be two random series that converge in $L^2(\Omega)$. Suppose that one of the series converges absolutely, say $\sum_{n=0}^{\infty} \|V_n\|_{L^2(\Omega)} < \infty$. Then:

$$\left(\sum_{n=0}^{\infty} U_n\right) \left(\sum_{n=0}^{\infty} V_n\right) = \sum_{n=0}^{\infty} W_n,$$

where:

$$W_n = \sum_{m=0}^n U_{n-m} V_m,$$

and $\sum_{n=0}^{\infty} W_n$ is understood in $L^1(\Omega)$. The series $\sum_{n=0}^{\infty} W_n$ is known as the Cauchy product of the series $\sum_{n=0}^{\infty} U_n$ and $\sum_{n=0}^{\infty} V_n$.

With these two auxiliary results, the main theorem of [17] was stated as follows:

Theorem 1 ([17] (Th. 3.3)). Let $A(t) = \sum_{n=0}^{\infty} A_n (t-t_0)^n$ and $B(t) = \sum_{n=0}^{\infty} B_n (t-t_0)^n$ be two random series in the $L^2(\Omega)$ setting, for $t \in (t_0-r,t_0+r)$, r>0 being finite and fixed. Assume that the initial conditions Y_0 and Y_1 belong to $L^2(\Omega)$. Suppose that there is a constant $C_r>0$, maybe dependent on r, such that

 $||A_n||_{L^{\infty}(\Omega)} \le C_r/r^n$ and $||B_n||_{L^{\infty}(\Omega)} \le C_r/r^n$, $n \ge 0$. Then, the stochastic process $X(t) = \sum_{n=0}^{\infty} X_n(t-t_0)^n$, $t \in (t_0-r,t_0+r)$, where:

$$X_0 = Y_0, \quad X_1 = Y_1,$$
 (2)

$$X_{n+2} = \frac{-1}{(n+2)(n+1)} \sum_{m=0}^{n} \left[(m+1)A_{n-m}X_{m+1} + B_{n-m}X_m \right], \ n \ge 0, \tag{3}$$

is the unique analytic solution to the random initial value problem (1) in the mean square sense.

This theorem is a generalization of the deterministic Fröbenius method to a random framework. As was demonstrated in [17], Theorem 1 has many applications in practice. It supposes a unified approach to study the most well-known second order linear random differential equations: Airy [8], Hermite [9], Legendre [10,11], Laguerre [12], and Bessel [13]. The results established in these articles [8–13] are particular cases of Theorem 1. The main reason why this fact occurs is explained in [17] (Section 3.3): given a random variable Z, the fact that its centered absolute moments grow at most exponentially, $\mathbb{E}[|Z|^n] \leq HR^n$ for certain H > 0 and R > 0, is equivalent to Z being essentially bounded, $\|Z\|_{L^\infty(\Omega)} \leq R$.

Notice that Theorem 1 does not require any independence assumption about the random input parameters. Moreover, from Theorem 1, [17] obtained error estimates for the approximation of the solution stochastic process, its mean, and its variance.

Let us see that Theorem 1 may be put in an easier to handle form. We substitute the growth condition on the coefficients A_0, A_1, \ldots and B_0, B_1, \ldots by the $L^{\infty}(\Omega)$ convergence of the random power series that define A(t) and B(t). In this manner, in practical applications, one does not need to find any constant C_r ; see the forthcoming Examples 1–4.

Theorem 2. Let $A(t) = \sum_{n=0}^{\infty} A_n (t-t_0)^n$ and $B(t) = \sum_{n=0}^{\infty} B_n (t-t_0)^n$ be two random series in the $L^{\infty}(\Omega)$ setting, for $t \in (t_0 - r, t_0 + r)$, r > 0 being finite and fixed. Assume that the initial conditions Y_0 and Y_1 belong to $L^2(\Omega)$. Then, the stochastic process $X(t) = \sum_{n=0}^{\infty} X_n (t-t_0)^n$, $t \in (t_0 - r, t_0 + r)$, whose coefficients are defined by (2) and (3), is the unique analytic solution to the random initial value problem (1) in the mean square sense.

Proof. By [11] (Lemma 2.3),

$$\sum_{n=0}^{\infty} \|A_n\|_{\mathrm{L}^{\infty}(\Omega)} |t-t_0|^n < \infty, \quad \sum_{n=0}^{\infty} \|B_n\|_{\mathrm{L}^{\infty}(\Omega)} |t-t_0|^n < \infty,$$

for $t \in (t_0 - r, t_0 + r)$. Thus, for each $0 \le r_1 < r$,

$$\sum_{n=0}^{\infty} \|A_n\|_{\mathrm{L}^{\infty}(\Omega)} r_1^n < \infty, \quad \sum_{n=0}^{\infty} \|B_n\|_{\mathrm{L}^{\infty}(\Omega)} r_1^n < \infty.$$

Since the sequences $\{\|A_n\|_{L^{\infty}(\Omega)}r_1^n\}_{n=0}^{\infty}$ and $\{\|B_n\|_{L^{\infty}(\Omega)}r_1^n\}_{n=0}^{\infty}$ tend to zero, they are both bounded by a number $C_{r_1} > 0$:

$$||A_n||_{L^{\infty}(\Omega)} \leq \frac{C_{r_1}}{r_1^n}, \quad ||B_n||_{L^{\infty}(\Omega)} \leq \frac{C_{r_1}}{r_1^n}, \quad n \geq 0.$$

Then, Theorem 1 is applicable with r_1 : the stochastic process $X(t) = \sum_{n=0}^{\infty} X_n (t-t_0)^n$ whose coefficients are given by (2) and (3) is a mean square solution to (1) on $(t_0 - r_1, t_0 + r_1)$. Now, since r_1 is arbitrary, we can extend this result to the whole interval $(t_0 - r, r_0 + r)$.

Notice that we have proven that Theorem 1 from [17] entails Theorem 2. However, the other way around also holds: Theorem 2 implies Theorem 1. Thus, both theorems are equivalent and offer the same information. Indeed, if we assume the hypotheses from Theorem 1, then:

$$||A_n||_{L^{\infty}(\Omega)}r_1^n \leq C_r \left(\frac{r_1}{r}\right)^n, \quad ||B_n||_{L^{\infty}(\Omega)} \leq C_r \left(\frac{r_1}{r}\right)^n,$$

for any $0 \le r_1 < r$, and since $\sum_{n=0}^{\infty} (\frac{r_1}{r})^n < \infty$, by comparison, we derive that:

$$\sum_{n=0}^{\infty} \|A_n\|_{\mathrm{L}^{\infty}(\Omega)} r_1^n < \infty, \quad \sum_{n=0}^{\infty} \|B_n\|_{\mathrm{L}^{\infty}(\Omega)} r_1^n < \infty,$$

which entails that the series of $A(t) = \sum_{n=0}^{\infty} A_n (t-t_0)^n$ and $B(t) = \sum_{n=0}^{\infty} B_n (t-t_0)^n$ converge $L^{\infty}(\Omega)$, by [11] (Lemma 2.3), for $t \in (t_0 - r_1, t_0 + r_1)$. As r_1 is arbitrary, the $L^{\infty}(\Omega)$ convergence holds for $t \in (t_0 - r, t_0 + r)$. This is exactly the hypothesis used in Theorem 2.

Let us see that Theorem 2 has an easier to handle form by checking the hypotheses in the examples from [17]. We refer the reader to [17] (Section 4) for approximations of the expectation and variance statistics of the solution stochastic process to each one of the examples.

Example 1. Airy's random differential equation is defined as follows:

$$\begin{cases} \ddot{X}(t) + AtX(t) = 0, \ t \in \mathbb{R}, \\ X(0) = Y_0, \\ \dot{X}(0) = Y_1, \end{cases}$$
(4)

where A, Y_0 , and Y_1 are random variables. We suppose that Y_0 and Y_1 have centered second order absolute moments. In [8], the hypothesis used in order to obtain a mean square analytic solution X(t) was $\mathbb{E}[|A|^n] \leq HR^n$, $n \geq n_0$. See [8] (expr. (18)–(19)) for the explicit expression of the solution process X(t). Notice that this growth assumption is equivalent to $||A||_{L^{\infty}(\Omega)} \leq R$, by [17] (Section 3.3). In our general notation, A(t) = 0 and B(t) = At. Due to the boundedness of the random variable A, the $L^{\infty}(\Omega)$ convergence of the series that define A(t) and B(t) holds, so Theorem 2 (and Theorem 1) is applicable: there is an analytic solution stochastic process X(t) to (4) on \mathbb{R} , whose coefficients are defined by (2) and (3).

Example 2. Hermite's random differential equation is given as follows:

$$\begin{cases} \ddot{X}(t) - 2t\dot{X}(t) + AX(t) = 0, \ t \in \mathbb{R}, \\ X(0) = Y_0, \\ \dot{X}(0) = Y_1, \end{cases}$$
 (5)

where A, Y_0 , and Y_1 are random variables. We suppose that Y_0 , $Y_1 \in L^2(\Omega)$. In [9], the hypothesis utilized to derive a mean square analytic solution X(t) was $\mathbb{E}[|A|^n] \leq HR^n$, $n \geq n_0$. See [9] (expr. (26)–(27)) for the explicit expression of the solution process X(t). This growth hypothesis is equivalent to $||A||_{L^{\infty}(\Omega)} \leq R$, by [17] (Section 3.3). Under the boundedness of the random variable A, the input stochastic processes A(t) = -2t and B(t) = A are expressible as $L^{\infty}(\Omega)$ convergent random power series. Hence, both Theorem 2 and Theorem 1 are applicable and guarantee the existence of a mean square solution process X(t) on \mathbb{R} , whose coefficients are defined by (2) and (3).

Example 3. We consider the following random linear differential equation with polynomial data processes:

$$\begin{cases}
\ddot{X}(t) + (A_0 + A_1 t)\dot{X}(t) + (B_0 + B_1 t)X(t) = 0, \ t \in \mathbb{R}, \\
X(0) = Y_0, \\
\dot{X}(0) = Y_1.
\end{cases}$$
(6)

If the initial conditions Y_0 and Y_1 belong to $L^2(\Omega)$ and the random input parameters A_0 , A_1 , B_0 , and B_1 are bounded random variables, then the hypotheses of Theorem 2 (and Theorem 1) are fulfilled, and we derive

that there is a mean square solution process X(t) on \mathbb{R} , with coefficients defined by (2) and (3). In contrast to Example 1 and Example 2, the partial sums of the series X(t) are not obtained explicitly. One computes the partial sums computationally via the recursion (2) and (3); see [17] (Example 4.3) for further details.

Example 4. We consider (1) with the non-polynomial analytic stochastic process:

$$\begin{cases} \ddot{X}(t) + A(t)\dot{X}(t) + B(t)X(t) = 0, \ t \in \mathbb{R}, \\ X(0) = Y_0, \\ \dot{X}(0) = Y_1, \end{cases}$$
 (7)

where $A_n \sim Beta(11,15)$, for $n \geq 0$, $B_n = 1/n^2$, for $n \geq 1$, and $Y_0, Y_1 \in L^2(\Omega)$. Since $\sum_{n=0}^{\infty} \|A_n\|_{L^{\infty}(\Omega)} |t|^n = \sum_{n=0}^{\infty} |t|^n$ is finite for $t \in (-1,1)$, and analogously for B(t), Theorem 2 (and consequently, Theorem 1) implies that there is a mean square solution X(t) to (7) on (-1,1), with coefficients expressed by (2) and (3). Unlike Example 1 and Example 2, the partial sums of the series X(t) are not obtained explicitly, and one acts computationally by means of the recursion (2) and (3); see [17] (Example 4.4) for details.

We raise the following open problem, which would imply that the hypotheses used in Theorem 2 are necessary: "If there exists a point $t_1 \in (t_0 - r, t_0 + r)$ such that $A(t_1) \notin L^{\infty}(\Omega)$ or $B(t_1) \notin L^{\infty}(\Omega)$, then there exist two initial conditions $Y_0, Y_1 \in L^2(\Omega)$ such that (1) has no mean square solution on $(t_0 - r, t_0 + r)$ ". Although we have not been able to prove this statement (which might be false), we think that the proof might be based on the reasoning used in [23] (Example, pp. 4–5).

This open problem, despite being of theoretical interest, does not contribute in practical applications. In numerical experiments, one usually truncates the stochastic processes A(t) and B(t) (that is, works with a partial sum instead of the whole Taylor series). This is not uncommon when dealing with stochastic systems computationally, as one requires a dimensionality reduction of the problem. If the coefficients of A(t) and/or B(t) have unbounded support, one may truncate them so that the hypotheses of Theorems 1 and 2 are fulfilled, and the probabilistic behavior of the data processes does not change much.

3. Non-Homogeneous Case

In this section, we generalize (1) by adding a stochastic source term:

$$\begin{cases} \ddot{X}(t) + A(t)\dot{X}(t) + B(t)X(t) = C(t), \ t \in \mathbb{R}, \\ X(t_0) = Y_0, \\ \dot{X}(t_0) = Y_1. \end{cases}$$
(8)

This new term C(t) is analytic at t_0 in the mean square sense [21] (p. 99), with Taylor series:

$$C(t) = \sum_{n=0}^{\infty} C_n (t - t_0)^n, \quad t \in (t_0 - r, t_0 + r).$$

The coefficients C_0 , C_1 , . . . are random variables. For this new model (8), we want to find conditions under which X(t) is an analytic mean square solution on $(t_0 - r, t_0 + r)$. This work was not done in [17], and it completes the study on the random non-autonomous second order linear differential equation with analytic input processes.

The following theorem is a generalization of Theorem 2:

Theorem 3. Let $A(t) = \sum_{n=0}^{\infty} A_n (t-t_0)^n$ and $B(t) = \sum_{n=0}^{\infty} B_n (t-t_0)^n$ be two random series in the $L^{\infty}(\Omega)$ setting, for $t \in (t_0 - r, t_0 + r)$, r > 0 being finite and fixed. Let $C(t) = \sum_{n=0}^{\infty} C_n (t-t_0)^n$ be a random series

in the mean square sense on (t_0-r,t_0+r) . Assume that the initial conditions Y_0 and Y_1 belong to $L^2(\Omega)$. Then, the stochastic process $X(t) = \sum_{n=0}^{\infty} X_n(t-t_0)^n$, $t \in (t_0-r,t_0+r)$, whose coefficients are defined by:

$$X_0 = Y_0, \quad X_1 = Y_1,$$
 (9)

$$X_{n+2} = \frac{1}{(n+2)(n+1)} \left\{ -\sum_{m=0}^{n} \left[(m+1)A_{n-m}X_{m+1} + B_{n-m}X_m \right] + C_n \right\}, \ n \ge 0,$$
 (10)

is the unique analytic solution to the random initial value problem (8) in the mean square sense.

Proof. Suppose that $X(t) = \sum_{n=0}^{\infty} X_n (t-t_0)^n$ is a solution to (8) in the $L^2(\Omega)$ sense, for $t \in (t_0 - r, t_0 + r)$. By Proposition 2 with p = 2, the mean square derivatives of X(t) are given by:

$$\dot{X}(t) = \sum_{n=1}^{\infty} n X_n (t - t_0)^{n-1} = \sum_{n=0}^{\infty} (n+1) X_{n+1} (t - t_0)^n,$$

$$\ddot{X}(t) = \sum_{n=2}^{\infty} n(n-1)X_n(t-t_0)^{n-2} = \sum_{n=0}^{\infty} (n+2)(n+1)X_{n+2}(t-t_0)^n.$$

By Proposition 3,

$$A(t)\dot{X}(t) = \sum_{n=0}^{\infty} \left(\sum_{m=0}^{n} A_{n-m}(m+1)X_{m+1} \right) (t-t_0)^n,$$

$$B(t)X(t) = \sum_{n=0}^{\infty} \left(\sum_{m=0}^{n} B_{n-m} X_m \right) (t - t_0)^n,$$

where these two random series converge in L¹(Ω). From $\ddot{X}(t) + A(t)\dot{X}(t) + B(t)X(t) = C(t)$,

$$\sum_{n=0}^{\infty} \left[(n+2)(n+1)X_{n+2} + \sum_{m=0}^{n} \left(A_{n-m}(m+1)X_{m+1} + B_{n-m}X_m \right) \right] (t-t_0)^n = \sum_{n=0}^{\infty} C_n (t-t_0)^n,$$

where the infinite series converge in $L^1(\Omega)$. By Proposition 2 with p = 1, differentiating over and over again in the $L^1(\Omega)$ sense and evaluating at $t = t_0$ yield:

$$(n+2)(n+1)X_{n+2} + \sum_{m=0}^{n} (A_{n-m}(m+1)X_{m+1} + B_{n-m}X_m) = C_n.$$

Isolating X_{n+2} , we obtain the recursive expression (10).

Thus, it only remains to prove that the random power series $X(t) = \sum_{n=0}^{\infty} X_n (t - t_0)^n$, whose coefficients are defined by (9) and (10), converges in the mean square sense.

From the hypothesis $Y_0, Y_1 \in L^2(\Omega)$ and by induction on n in Expression (10), we obtain that $X_n \in L^2(\Omega)$ for all $n \geq 0$. On the other hand, by [11] (Lemma 2.3),

$$\sum_{n=0}^{\infty} \|A_n\|_{L^{\infty}(\Omega)} s^n < \infty, \ \sum_{n=0}^{\infty} \|B_n\|_{L^{\infty}(\Omega)} s^n < \infty, \ \sum_{n=0}^{\infty} \|C_n\|_{L^{2}(\Omega)} s^n < \infty,$$

for 0 < s < r. As the general term of a convergent series tends to zero, we have the following bounds:

$$||A_n||_{L^{\infty}(\Omega)} \le \frac{D_s}{s^n}, ||B_n||_{L^{\infty}(\Omega)} \le \frac{D_s}{s^n}, ||C_n||_{L^2(\Omega)} \le \frac{D_s}{s^n}, n \ge 0,$$
 (11)

for a certain constant $D_s > 0$ that depends on s. Then, from (10), if we apply $L^2(\Omega)$ norms and (11), we obtain:

$$||X_{n+2}||_{L^{2}(\Omega)} \leq \frac{1}{(n+2)(n+1)} \left\{ \sum_{m=0}^{n} \left[(m+1) ||A_{n-m}X_{m+1}||_{L^{2}(\Omega)} + ||B_{n-m}X_{m}||_{L^{2}(\Omega)} \right] + ||C_{n}||_{L^{2}(\Omega)} \right\}$$

$$\leq \frac{1}{(n+2)(n+1)} \frac{D_{s}}{s^{n}} \left\{ \sum_{m=0}^{n} s^{m} \left((m+1) ||X_{m+1}||_{L^{2}(\Omega)} + ||X_{m}||_{L^{2}(\Omega)} \right) + 1 \right\}.$$

$$(12)$$

Define $H_0 := ||Y_0||_{L^2(\Omega)}$, $H_1 := ||Y_1||_{L^2(\Omega)}$, and:

$$H_{n+2} := \frac{1}{(n+2)(n+1)} \frac{D_s}{s^n} \left\{ \sum_{m=0}^n s^m \left((m+1)H_{m+1} + H_m \right) + 1 \right\}, \quad n \ge 0.$$
 (13)

From (12) and (13), by induction on n, it is trivially seen that $||X_n||_{L^2(\Omega)} \le H_n$, for $n \ge 0$. If we check that $\sum_{n=0}^{\infty} H_n \rho_1^n < \infty$, for all $0 < \rho_1 < s < r$, then the random series that defines X(t) converges in the mean square sense on $(t_0 - r, t_0 + r)$, as wanted.

We rewrite (13) so that H_{n+2} is expressed as a function of H_{n+1} and H_n (second order recurrence equation). By assuming $n \ge 1$, we perform the following operations:

$$H_{n+2} = \frac{1}{(n+2)(n+1)} \frac{D_s}{s^n} \left(\sum_{m=0}^{n-1} s^m \left((m+1)H_{m+1} + H_m \right) + 1 + s^n \left((n+1)H_{n+1} + H_n \right) \right)$$

$$= \frac{1}{(n+2)(n+1)} \frac{D_s}{s^n} \frac{(n+1)n}{D_s} s^{n-1} \left(\underbrace{\frac{1}{(n+1)n} \frac{D_s}{s^{n-1}} \left\{ \sum_{m=0}^{n-1} s^m \left((m+1)H_{m+1} + H_m \right) + 1 \right\}}_{=H_{n+1}} \right)$$

$$+ \frac{D_s}{n+2} H_{n+1} + \frac{D_s}{(n+2)(n+1)} H_n$$

$$= \left(\frac{n}{(n+2)s} + \frac{D_s}{n+2} \right) H_{n+1} + \frac{D_s}{(n+2)(n+1)} H_n.$$
(14)

This difference equation of order two has as initial conditions:

$$H_2 = \frac{D_s}{2} (H_1 + H_0 + 1), \quad H_1 = ||Y_1||_{L^2(\Omega)}, \quad H_0 = ||Y_0||_{L^2(\Omega)}.$$

Notice that H_2 is obtained from (13). Expression (14) coincides with [17] (expr. (12)) (although with different initial conditions). Then, the method of proof for $\sum_{n=0}^{\infty} H_n s^n < \infty$ is identical to the last part of the proof of [17] (Th. 3.3). Indeed, fixing $0 < \rho_1 < \rho < s$, we have:

$$H_{n+2}\rho^{n+2} = \left(\frac{n\rho}{(n+2)s} + \frac{D_s\rho}{n+2}\right)H_{n+1}\rho^{n+1} + \frac{D_s\rho^2}{(n+2)(n+1)}H_n\rho^n.$$

Let $M_n = \max_{0 \le m \le n} H_m \rho^m$. We have:

$$H_{n+2}\rho^{n+2} \le \left(\frac{n\rho}{(n+2)s} + \frac{D_s\rho}{n+2} + \frac{D_s\rho^2}{(n+2)(n+1)}\right)M_{n+1}.$$

Since:

$$\lim_{n \to \infty} \frac{n\rho}{(n+2)s} + \frac{D_s \rho}{n+2} + \frac{D_s \rho^2}{(n+2)(n+1)} = \frac{\rho}{s} < 1,$$

it holds $M_{n+2} = M_{n+1}$ for all large n, and call the common value M. Hence, $H_n \rho^n \leq M$ for all large n, therefore, $H_n \rho_1^n \leq M(\rho_1/\rho)^n$. Since $\sum_{n=0}^{\infty} (\rho_1/\rho)^n < \infty$, by comparison, the series $\sum_{n=0}^{\infty} H_n \rho_1^n$ converges, and we are done. \square

Example 5. Let us consider Hermite's random differential equation with a stochastic source term:

$$\begin{cases} \ddot{X}(t) - 2t\dot{X}(t) + AX(t) = Ct^2, \ t \in \mathbb{R}, \\ X(0) = Y_0, \\ \dot{X}(0) = Y_1, \end{cases}$$
 (15)

where A, C, Y_0 , and Y_1 are random variables. Due to the non-homogeneity of the equation, this example cannot be addressed with [17]. We have set the following probability distributions:

$$A \sim \textit{Bernoulli}(0.35), \quad Y_0 \sim \textit{Gamma}(2,2), \quad (Y_1,C) \sim \textit{Multinomial}(3,\{0.2,0.8\})$$

(for the Gamma distribution, we use the shape-rate notation) where A, Y_0 and (Y_1,C) are independent. Notice that we are considering both discrete and absolutely continuous random variables/vectors and also both independent and non-independent random variables/vectors. Thus, the Fröbenius method covers a wide variety of situations in practice. Since A is bounded and $Y_0, Y_1, C \in L^2(\Omega)$, Theorem 3 ensures that the random power series $X(t) = \sum_{n=0}^{\infty} X_n(t-t_0)^n$ defined recursively by (9) and (10) is a mean square solution to (15) on \mathbb{R} . By considering the partial sums $X^N(t) = \sum_{n=0}^N X_n(t-t_0)^n$, we approximate the expectation and variance of X(t) as:

$$\mathbb{E}[X(t)] = \lim_{N \to \infty} \mathbb{E}[X_N(t)], \quad \mathbb{V}[X(t)] = \lim_{N \to \infty} \mathbb{V}[X_N(t)],$$

see Proposition 1. The computations have been performed in the software Mathematica[®]. Our code to build the partial sum $X^N(t)$ was the following one:

```
 \begin{split} &X[n_?NonPositive] := Y0; \\ &X[1] = Y1; \\ &X[n_] := 1/(n*(n-1))*(-Sum[(m+1)*A[n-2-m]*X[m+1] + B[n-2-m]*X[m], \{m, 0, n-2\}] + CC[n-2]); \\ &seriesX[t_, t0_, N_] := X[0] + Sum[X[n]*(t-t0)^n, \{n, 1, N\}]; \end{split}
```

This implementation in the computer is necessary, as no closed-form expression for $X^N(t)$ is available due to the complexity of (15). For each numeric value of \mathbb{N} , the functions $t \mapsto \mathbb{E}[X^N(t)]$ and $t \mapsto \mathbb{V}[X^N(t)]$ have been calculated with the built-in function Expectation applied to series $\mathbb{X}[t, 0, \mathbb{N}]$ (with symbolic t), by setting the desired probability distributions to $\mathbb{A}[n]$, $\mathbb{B}[n]$, and $\mathbb{CC}[n]$. In Tables 1 and 2, we show $\mathbb{E}[X^N(t)]$ and $\mathbb{V}[X^N(t)]$ for N=19, N=20, and $0 \le t \le 1.5$. Both orders of truncation produce similar results, which agrees with the theoretical convergence. Observe that, as we move away from the initial condition $t_0=0$, larger orders of truncation are needed. This indicates that the Fröbenius method might be computationally inviable for large t. The results have been compared with Monte Carlo simulation (with 100,000 and 200,000 realizations).

t	$\mathbb{E}[X^{19}(t)]$	$\mathbb{E}[X^{20}(t)]$	MC 100,000	MC 200,000
0.00	1	1	0.995893	1.00266
0.25	1.14231	1.14231	1.13899	1.14544
0.50	1.28890	1.28890	1.28672	1.29236
0.75	1.49183	1.49183	1.49130	1.49547
1.00	1.85892	1.85892	1.86087	1.86246
1.25	2.62573	2.62574	2.63173	2.62863
1.50	4.34772	4.34784	4.36111	4.34892

Table 1. Approximation of $\mathbb{E}[X(t)]$ with N=19, N=20, and Monte Carlo simulations. Example 5.

t	$\mathbb{V}[X^{19}(t)]$	$\mathbb{V}[X^{20}(t)]$	MC 100,000	MC 200,000
0.00	0.5	0.5	0.493124	0.504501
0.25	0.520298	0.520298	0.514702	0.524803
0.50	0.597008	0.597008	0.593603	0.601376
0.75	0.790556	0.790556	0.790161	0.794549
1.00	1.27425	1.27425	1.27702	1.27759
1.25	2.60694	2.60694	2.60987	2.60982
1.50	6.94095	6.94100	6.92663	6.94787

Table 2. Approximation of $\mathbb{V}[X(t)]$ with N = 19, N = 20, and Monte Carlo simulations. Example 5.

Notice that the theoretical error estimates from [17] (Section 3.6) apply in this case as well, since all estimates rely on the majorization $\|X_n\|_{L^2(\Omega)} \le H_n$ and the recursive Equation (14), which also hold in [17].

An important issue that was not treated in the recent contribution [17] is the uniqueness of the mean square solution. To deal with uniqueness, we use a habitual extension of the classical Picard theorem to mean square calculus [21] (Th. 5.1.2); see Theorem 4. Notice that, in our setting of analyticity for A(t) and B(t) in the $L^{\infty}(\Omega)$ sense, one has that A(t) and B(t) are continuous in $L^{\infty}(\Omega)$, so the uniqueness from Theorem 4 is applicable.

Theorem 4. If A(t) and B(t) are continuous stochastic processes in the $L^{\infty}(\Omega)$ sense, then the mean square solution to (8) is unique.

Proof. We write (1) as a first order random differential equation, which is the setting under study in [21]:

$$\underbrace{\begin{pmatrix} \dot{X}(t) \\ \dot{X}(t) \end{pmatrix}}_{\dot{Z}(t)} = \underbrace{\begin{pmatrix} 0 & 1 \\ -B(t) & -A(t) \end{pmatrix}}_{M(t)} \underbrace{\begin{pmatrix} X(t) \\ \dot{X}(t) \end{pmatrix}}_{Z(t)} + \underbrace{\begin{pmatrix} 0 \\ C(t) \end{pmatrix}}_{q(t)}.$$

We work in the space $L^2_2(\Omega)$ of two-dimensional random vectors whose components belong to $L^2(\Omega)$. Given $Z=(Z_1,Z_2)\in L^2_2(\Omega)$, its norm is defined as:

$$||Z||_{L^2(\Omega)} = \max\{||Z_1||_{L^2(\Omega)}, ||Z_2||_{L^2(\Omega)}\}.$$

On the other hand, given a random matrix $B = (B_{ij})$, we define the following norm:

$$|||B||| = \max_{i} \sum_{j} ||B_{ij}||_{L^{\infty}(\Omega)}.$$

In the case of the random matrix M(t), it holds:

$$|||M(t)||| = \max\{1, ||A(t)||_{L^{\infty}(\Omega)} + ||B(t)||_{L^{\infty}(\Omega)}\}.$$
(16)

Given $Z, Z' \in L_2^2(\Omega)$, we have:

$$\|(M(t)Z+q(t))-(M(t)Z'+q(t))\|_{\mathrm{L}_{2}^{2}(\Omega)}=\|M(t)(Z-Z')\|_{\mathrm{L}_{2}^{2}(\Omega)}\leq \underbrace{\||M(t)|\|}_{k(t)}\cdot \|Z-Z'\|_{\mathrm{L}_{2}^{2}(\Omega)}.$$

Since A(t) and B(t) are continuous stochastic processes in the $L^{\infty}(\Omega)$ sense, the real maps:

$$t \in (t_0 - r, t_0 + r) \mapsto ||A(t)||_{L^{\infty}(\Omega)}, \quad t \in (t_0 - r, t_0 + r) \mapsto ||B(t)||_{L^{\infty}(\Omega)}$$

are continuous. By (16), the deterministic function k(t) is continuous on $(t_0 - r, t_0 + r)$. This implies that $k \in L^1([t_0 - r_1, t_0 + r_1])$ for each $0 < r_1 < r$. By [21] (Th. 5.1.2), there is the uniqueness of the mean square solution for (1) on $[t_0 - r_1, t_0 + r_1]$. Since r_1 is arbitrary, there is the uniqueness of the solution on $(t_0 - r, t_0 + r)$. \square

4. Comparison with Other Methods

A final objective of this paper is to relate our method based on [17] (which is based on the deterministic Fröbenius method) to other well-known techniques to tackle (8). In [17], the random power series method was compared, both theoretically and in numerical experiments, with Monte Carlo simulations and the dishonest method [24]. It was demonstrated that Monte Carlo simulations imply a more expensive computational cost to calculate accurately the expectation and variance

statistics for t near t_0 , due to the slow rate of convergence. However, Monte Carlo simulations usually allow validating the numerical results obtained, as they always present convergence with a similar rate for every stochastic system [25] (p. 53).

The article [17] does not compare the Fröbenius method with generalized polynomial chaos (gPC) expansions [25–30], although it has been proven to be a powerful technique to deal with general continuous and discrete stochastic systems with absolutely continuous random input coefficients. Due to the spectral mean square convergence of the Galerkin projections, the expectation and variance statistics of the response process can be approximated with small orders of truncation. In the particular setting of random second order linear differential equations, only [31,32] analyzed the application of gPC expansions to Airy's random differential equation, by assuming independence between the random input parameters. Recently, we have also studied the application of gPC expansions to the Legendre random differential equation with statistically-dependent inputs in an arXiv preprint [11]. The application of gPC expansions to general random second order linear differential equations (8) could be part of a future work. We believe that this is important because both the Fröbenius method and gPC expansions may validate each other in applications, since they provide good approximations of the expectation and variance statistics rapidly. Moreover, we believe that the gPC approach may provide better approximations of the statistics in the case of large times; see for example [33], where for the classical continuous epidemic models (SIS, SIR, etc.) uncertainty quantification is performed via gPC up to Time 60 with chaoses bases of order just two and three, producing very similar results; or [30], where an analogous study was performed for the corresponding discrete epidemiological models up to Time 30. Nonetheless, an excessively large number of input parameters may pose problems to the gPC-based method: if the chaos order is p and the degree of uncertainty is s, then the length of the basis for the gPC expansions is (p+s)!/(p!s!) [25], which may make the method computationally inviable. Another drawback of the gPC technique is that catastrophic numerical errors usually appear for large chaos orders, specially when dealing with truncated distributions ([11] (Example 4.3) and [34]).

In [17], we did not compare our methodology with the random differential transform method proposed in [35]. Given a stochastic process U(t), its random differential transform is defined as:

$$\hat{U}(k) = \frac{U^{(k)}(t_0)}{k!}.$$

Its inverse transform is defined as:

$$U(t) = \sum_{k=0}^{\infty} \hat{U}(k)(t - t_0)^k.$$

Notice that we are actually considering Taylor series in a random calculus setting. It is formally assumed that the series $\sum_{k=0}^{\infty} \hat{U}(k)(t-t_0)^k$ is mean square convergent on an interval (t_0-r,t_0+r) , r>0. The computations with the random differential transform method were analyzed in [35] (Th. 2.1).

Proposition 4 ([35] (Th. 2.1)). Let F(t) and G(t) be two second order stochastic processes, with mean square derivatives of k order $F^{(k)}(t)$ and $G^{(k)}(t)$. Then, the following results hold:

- (i) If $U(t) = F(t) \pm G(t)$, then $\hat{U}(k) = \hat{F}(k) \pm \hat{G}(k)$.
- (ii) If $U(t) = \lambda F(t)$, where λ is a bounded random variable, then $\hat{U}(k) = \lambda \hat{F}(k)$.
- (iii) If $U(t) = G^{(m)}(t)$, then $\hat{U}(k) = (k+1)\cdots(k+m)\hat{G}(k+m)$ (here, m is a nonnegative integer).
- (iv) If U(t) = F(t)G(t), then $\hat{U}(k) = \sum_{n=0}^{k} \hat{F}(n)\hat{G}(k-n)$.

Notice that (iii) and (iv) can be seen as consequences of differentiating random power series [17] (Th. 3.1) (Proposition 2) and multiplying random power series [17] (Th. 3.2) (Proposition 3), respectively.

Thereby, the random transform method is actually the random Fröbenius method. The recursive equations found for $\hat{X}(k)$ are as in (3). Our Theorems 1–3 give the conditions under which the inverse transform $\sum_{k=0}^{\infty} \hat{X}(k)(t-t_0)^k$ converges.

Thus, we believe that our recent contribution [17] together with the notes presented in this paper give an excellent approach to tackle (1) and/or (8) with analytic random input processes. Apart from obtaining a mean square analytic solution to (1) and/or (8), the expectation and variance of it can be calculated for uncertainty quantification.

5. Summary, Conclusions, and Future Lines of Research

In this paper, we have written some notes and comments to complete our recent contribution [17] on the random non-autonomous second order linear differential equation. The main theorem from [17], which deals with the homogeneous case, has been restated in a more convenient form to deal with practical applications. We addressed the non-homogeneous case, by proving an existence theorem of the mean square solution and performing a numerical example. On the other hand, the uniqueness of the solution has been established by using the Picard theorem for mean square calculus. A comparison of the extant techniques for uncertainty quantification (Monte Carlo, gPC expansions, random differential transform method) with respect to the random Fröbenius method was studied.

This paper is a contribution to the field of random differential equations, as it completely generalizes to a random framework the deterministic theory on second order linear differential equations with analytic input data. To carry out the study, mean square calculus and, in general, L^p random calculus become powerful tools to establish the theoretical results and perform uncertainty quantification.

Some future research lines related to the contents of this paper are the following:

- Solve the open problem raised in this paper at the end of Section 2, concerning the necessity of the hypotheses of Theorem 2.
- Apply the technique of gPC expansions and stochastic Galerkin projections to general random second order linear differential equations.
- Extend Theorem 3 to higher order random linear differential equations. Probably, one would need to require all input stochastic processes to be random power series in an L^{∞} sense, in analogy with the hypotheses of Theorem 3.
- Apply the random Fröbenius method to the random Riccati differential equation with the analytic input processes. In [35] (Section 3), the authors applied the random differential transform method (which is equivalent to a formal random Fröbenius method) to a particular case of the random Riccati differential equation with a random autonomous coefficient term. It would be interesting to apply the random Fröbenius method in the situation in which all input coefficients are analytic stochastic processes, by proving theoretical results and performing numerical experiments.

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