

1 **EFFECT ON MANUAL SKILLS OF WEARING INSTRUMENTED GLOVES DURING**  
2 **MANIPULATION**

3 Alba Roda-Sales<sup>1</sup>, Joaquín L. Sancho-Bru<sup>1</sup>, Margarita Vergara<sup>1</sup>, Verónica Gracia-Ibáñez<sup>1</sup>,  
4 Néstor J. Jarque-Bou<sup>1</sup>

5  
6 <sup>1</sup> Departamento de Ingeniería Mecánica y Construcción, Universitat Jaume I, Castelló de la  
7 Plana, Spain

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9 **Corresponding author:** Alba Roda-Sales (rodaa@uji.es)

10 Departamento de Ingeniería Mecánica y Construcción, Universitat Jaume I.

11 Av. de Vicent Sos Baynat, s/n. Castelló de la Plana, Castelló, Spain. E-12071

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18 **ABSTRACT**

19 Instrumented gloves are motion capture systems that are widely used due to the simplicity of the  
20 setup required and the absence of occlusion problems when manipulating objects. Nevertheless,  
21 the effect of their use on manipulation capabilities has not been studied to date. Therefore, the  
22 aim of this work is to quantify the effect of wearing CyberGlove instrumented gloves on these  
23 capabilities when different levels of precision are required. Thirty healthy subjects were asked to  
24 perform three standardised dexterity tests twice: bare-handed and wearing instrumented gloves.  
25 The tests were the Sollerman Hand Function Test (to evaluate capability of performing activities  
26 of daily living), the Box and Block Test (to evaluate gross motor skills) and the Purdue Pegboard  
27 Test (to evaluate fine motor skills). Scores obtained in the test evaluating fine motor skills  
28 decreased by an average of 29% when wearing gloves, while scores obtained on those evaluating  
29 gross motor skills and capability to perform activities of daily living were reduced by an average  
30 of 8% and 3%, respectively. The use of instrumented gloves to record hand kinematics is only  
31 recommended when performing tasks requiring medium and gross motor skills.

32

**33 1. INTRODUCTION**

34 Instrumented gloves are motion capture systems widely used due to the setup simplicity and the  
35 absence of occlusions when manipulating objects (common drawback in optical systems). They  
36 have been applied for different purposes in biomechanics: in hand kinematics applied for patients'  
37 functional assessments (Gracia-Ibáñez et al., 2017; Schreck et al., 2018), sign language  
38 recognition (Sarawate et al., 2015), precision gesture control in surgery (Itkowitz et al., 2018;  
39 Lemos et al., 2017), simulation (Nogueira et al., 2019; Sancho-Bru et al., 2014), validating other  
40 motion data systems (El-Sawah et al., 2007; Glauser et al., 2019), and for characterising hand  
41 dynamics combined with EMG recording (Jarque-Bou et al., 2018; Naik et al., 2014; Stival et al.,  
42 2019). Some of these applications only use joint angles, while others also consider joint velocity  
43 and acceleration. The analysed tasks covered a wide range of activities with different  
44 manipulation precisions, from fine to gross manipulations, and also non-manipulative activities.  
45 Nevertheless, work gloves affect grasping and manipulation capabilities, which leads us to  
46 wonder about the effect of using instrumented gloves on manual skills such as CyberGlove  
47 (CyberGlove Systems, San Jose, CA, USA), the most widely used in biomechanics (Jarque-Bou  
48 et al., 2019; Jarrassé et al., 2014; Yun and Freivalds, 1995).

49 In order to evaluate work gloves effects on dexterity, some studies propose indicators such as the  
50 index of dexterity in manipulation (using O'Connor and Purdue Pegboard tests (Bensel, 1993;  
51 Berger et al., 2009; Johnson and Sleeper, 1986) or other non-standardised tasks such as pegboard  
52 tasks, block manipulation, rope knotting or assembly tasks (Bishu et al., 1993; Muralidhar et al.,  
53 1999)), touch sensitivity using the Semmes-Weinstein monofilament test set (Dianat et al., 2012,  
54 2010), grip strength (Dianat et al., 2012, 2010; Muralidhar et al., 1999; Torrens and Newman,  
55 2000; Willms et al., 2009) or range of motion (Bellingar and Slocum, 1993). These studies show  
56 that using work gloves reduces dexterity (Bishu et al., 1993; Dianat et al., 2010; Johnson and  
57 Sleeper, 1986; Muralidhar et al., 1999). Such reductions vary from a slight decrease in dexterity  
58 test scores (Nelson and Mital, 1995) to increases of up to 87% in the time of accomplishment of  
59 the test (Torrens and Newman, 2000), depending on the glove characteristics. Dexterity reduction

60 depends on the glove material and thickness (Banks, 1979; Benseel, 1993; Muralidhar et al., 1999;  
61 Plummer et al., 1985), and is greater for stiff and bulky materials such as leather (Torrens and  
62 Newman, 2000) than for thinner materials such as latex (Nelson and Mital, 1995).

63 Given the effects of using work gloves reported in literature, the aim of this work is to quantify  
64 the effect of using a CyberGlove on manual skills when performing tasks requiring different  
65 degrees of precision, which is still unknown. This will help establishing the limitations of using  
66 the glove in biomechanics, especially in research applications where specific kinematic  
67 parameters are quantified. The analysis was performed using three different standardised tests:  
68 the Box & Block Test (BBT), which evaluates gross motor skills; the Purdue Pegboard Test  
69 (PPT), which evaluates fine motor skills, and the Sollerman Hand Function Test (SHFT), which  
70 focuses on the capability to perform activities of daily living (ADL).

## 71 **2. METHODS**

### 72 **2.1. SUBJECTS**

73 Thirty healthy adult subjects (16 male, 14 female;  $37.83 \pm 8.07$  years of age) participated in the  
74 experiment, approved by the University ethics committee, after signing their written informed  
75 consent. Subjects' laterality (27 right-handed and 3 left-handed) was determined using the  
76 Edinburgh Handedness Inventory (Oldfield, 1971).

### 77 **2.2. MATERIAL**

78 One left- and one right-hand CyberGlove were used, together with the kits for the three  
79 standardised tests (Figure 2): BBT (Mathiowetz et al., 1985) to evaluate gross motor skills, PPT  
80 (Tiffin and Asher, 1948) to fine motor skills and SHFT (Sollerman and Ejeskär, 1995), which  
81 evaluates the capability to perform ADL. CyberGlove is made of a synthetic elastic mesh fabric  
82 on the palm side, and a denser synthetic elastic fabric on the back in which the 18 resistive bend-  
83 sensors and the wiring are embedded. Following the manufacturer's instructions, a thin nylon  
84 inner glove is worn to keep the CyberGlove clean and in good condition. The tips of the fingers  
85 are covered only by the inner glove (Figure 1). The CyberGlove is worn and secured with a Velcro

86 strap around the wrist. An elastic band around the wrist, commonly used during recordings, was  
87 used to ensure a better fit of the wrist sensors.



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89 *Figure 1: Dorsal and palmar views of the CyberGlove instrumented glove used in the experiments.*

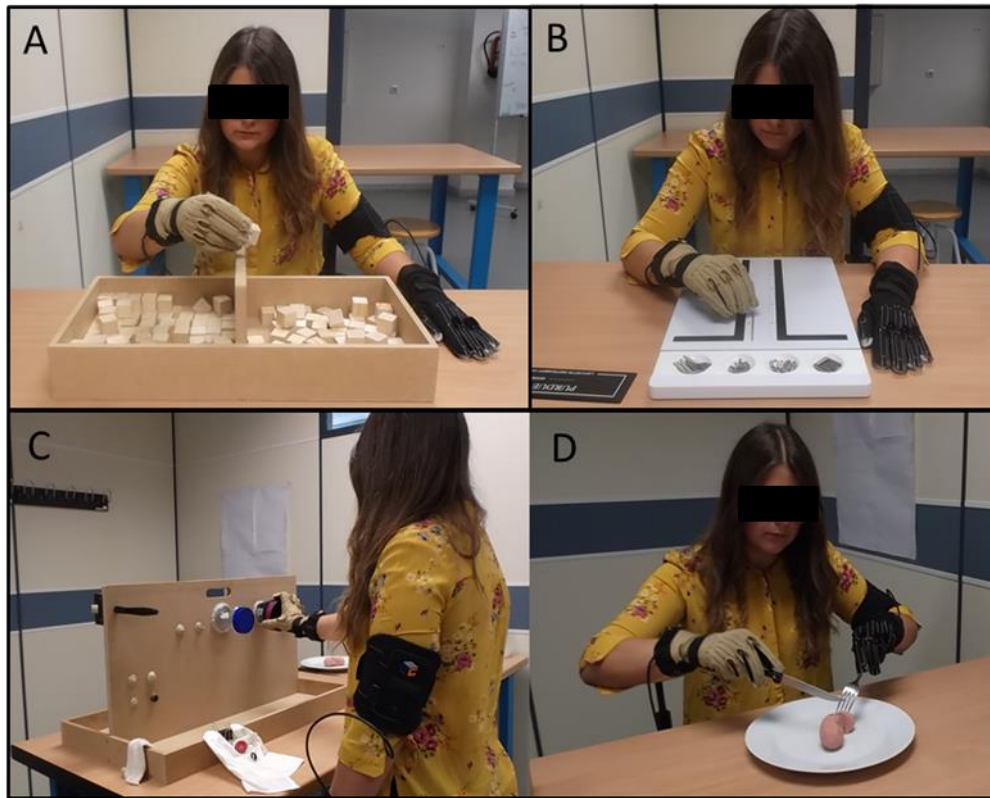
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91 Note that gloves were not acquiring data during the tests, as our aim was to compare just the  
92 scores of the dexterity tests while wearing gloves and bare-handed.

### 93 **2.3. EXPERIMENTS**

94 Each subject performed the three tests twice (bare-handed and wearing the gloves on both hands),  
95 the order being randomised for each participant. The experiment was divided into two sessions,  
96 in order to prevent subjects from getting tired. Thus, the BBT and PPT tests were conducted in  
97 the first session and the SHFT during the second session. Each test was performed following its  
98 standardised instructions. The BBT (Figure 2a) comprises one trial for each hand, in which the  
99 subject has to pass wooden blocks from one box to another within 60 seconds (Mathiowetz et al.,  
100 1985). The PPT (Figure 2b) comprises four trials: the first three trials consist in putting pins into  
101 holes on a board within 60 seconds (with the right hand, the left hand and simultaneously with  
102 both hands), and the fourth consists in assembling pins and washers with both hands (Tiffin and  
103 Asher, 1948). The SHFT (Figure 2c and Figure 2d) involves performing 20 tasks that are

104 representative of ADL, following the operator's instructions, which include whether subjects have  
105 to use both hands or only the dominant one (Sollerman and Ejeskär, 1995). The subjects were  
106 asked to perform all the tests at the maximum possible pace, but abiding by the test rules.



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108 *Figure 2: The different tests performed in the experiment. (a) Box & Block Test, (b) Purdue Pegboard Test, (c, d)*  
109 *Sollerman Hand Function Test.*  
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## 111 2.4. DATA ANALYSIS

112 Results from the tests were measured according to their standardised scorings:

- 113 - BBT: blocks passed in each trial.
- 114 - PPT: pieces assembled in each trial.
- 115 - SHFT: each task is assigned a five-level score according to the type of grasp used, the  
116 level of difficulty observed and the time of accomplishment of the task (4 when the  
117 accomplishment is as expected, 0 when the task is not performed). A global score is  
118 computed as the sum of these 20 scores.

119 The reductions in scores due to the instrumented gloves were computed for each subject and trial.  
 120 Descriptive statistics are presented. Seven repeated-measures ANOVAs were performed on the  
 121 scores of each BBT and PPT test, and on the global score of the SHFT. In all cases, the factor was  
 122 the use of gloves, to determine its effect on the manual skills assessed by each test. The dependent  
 123 variables in the seven ANOVAs were BBT score with right hand, BBT score with left hand, PPT  
 124 score with right hand, PPT score with left hand, PPT with both hands and SHFT global score.  
 125 Furthermore, a detailed analysis of the SHFT tasks was performed through their individual scores  
 126 and times of accomplishment. Twenty repeated-measure ANOVAs, one for each task, were  
 127 performed on scores and times as dependent variables, again with the use of gloves as the factor.  
 128 Moreover, score variation and time increase percentages when using gloves were computed for  
 129 each task.

### 130 3. RESULTS

131 Table 1 presents the descriptive statistics (mean and standard deviation) of the scores and their  
 132 reductions for BBT, PPT and SHFT trials. Significant differences from the ANOVAs are marked.  
 133 As expected, scores when wearing gloves are lower than those achieved without them. The seven  
 134 ANOVAs for the test scores were significant (bilateral asymptotic significance  $\leq 0.01$ ), showing  
 135 that the use of gloves affects all types of dexterity analysed.

136 *Table 1: Mean (SD) scores and mean (SD) reduction of scores obtained for BBT, PPT and SHFT. Tests “PPT Both*  
 137 *1” when putting the pins in the pegboard with both hands simultaneously, and “PPT Both 2” when performing the*  
 138 *assembly task (both hands). Tests with significant differences (sig.  $\leq 0.01$ ) in the repeated measures ANOVAs have*  
 139 *been marked (\*\*).*

Test	Score without glove	Score with glove	Score reduction (%)
<b>BBT Right**</b>	80.23 (8.46)	74.23 (9.55)	7.32 (9.73)
<b>BBT Left**</b>	76.77 (7.24)	70.27 (7.56)	8.37 (6.30)
<b>PPT Right**</b>	16.93 (2.16)	12.73 (2.16)	24.47 (11.17)
<b>PPT Left**</b>	15.17 (2.00)	11.73 (1.89)	22.16 (11.91)
<b>PPT Both 1**</b>	25.40 (3.33)	18.20 (3.69)	27.75 (14.91)
<b>PPT Both 2**</b>	44.13 (6.86)	25.57 (8.34)	41.76 (18.72)
<b>SHFT**</b>	74.07 (1.70)	72.07 (2.13)	2.68 (2.79)

140 Table 2 presents the descriptive statistics for the individual scores of the SHFT tasks. Significant  
 141 differences from the ANOVAs are marked. All the tasks with significant differences presented a  
 142 decrease in scores when performed with gloves.

143 *Table 2: Mean (SD) scores obtained in each SHFT task and percentage of score difference (negative values for*  
 144 *decrease in dexterity with gloves). Tasks with significant differences (sig.  $\leq 0.01$ ) in the repeated measures ANOVAs*  
 145 *have been marked (\*\*).*

ID	Task	Score without glove	Score with glove	Score difference (%)
1	Pick up coins from flat surface, put into a purse mounted on wall	4.00 (0.00)	3.87 (0.43)	-3.33 (10.85)
2	Open/close zip	4.00 (0.00)	4.00 (0.00)	0.00 (0.00)
3	Pick up coins from purses**	3.93 (0.25)	3.37 (0.67)	-13.89 (18.87)
4	Lift wooden cubes over edge 5cm in height	4.00 (0.00)	4.00 (0.00)	0.00 (0.00)
5	Lift iron over edge 5cm in height	3.93 (0.36)	3.93 (0.36)	+1.67 (20.69)
6	Turning screw with screwdriver	3.87 (0.51)	4.00 (0.00)	+6.66 (25.37)
7	Pick up nuts and screw on bolts**	3.47 (0.51)	2.90 (0.61)	-15.00 (21.37)
8	Put key into lock, turn 90 degrees	4.00 (0.00)	4.00 (0.00)	0.00 (0.00)
9	Turn door-handle 30°	3.93 (0.36)	4.00 (0.00)	+3.33 (18.25)
10	Unscrew lid of jars	2.73 (0.98)	2.87 (1.01)	+8.33 (32.38)
11	Do up buttons**	3.90 (0.30)	3.37 (0.49)	-13.05 (15.11)
12	Put on tubigrip stocking on the other hand	4.00 (0.00)	3.93 (0.25)	-1.67 (6.34)
13	Cut play dough with knife and fork	4.00 (0.00)	3.97 (0.18)	-0.83 (4.56)
14	Write with a pen	4.00 (0.00)	4.00 (0.00)	0.00 (0.00)
15	Fold sheet of paper and put into envelope**	3.80 (0.41)	3.13 (0.57)	-16.67 (17.51)
16	Put a paper-clip on an envelope	4.00 (0.00)	4.00 (0.00)	0.00 (0.00)
17	Lift telephone receiver, put to ear	3.93 (0.36)	4.00 (0.00)	+3.33 (18.26)
18	Pour water from carton	2.10 (0.40)	2.13 (0.43)	+3.33 (22.49)
19	Pour water from jug	4.00 (0.00)	4.00 (0.00)	0.00 (0.00)
20	Pour water from cup	2.47 (0.86)	2.60 (1.07)	+10.00 (46.23)

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147 Table 3 shows the detailed analysis for the time of accomplishment of each SHFT task. Again,  
 148 significant differences in the ANOVAs are marked. When wearing gloves, times were higher in  
 149 all the tasks and significant differences were found in all the tasks except two.

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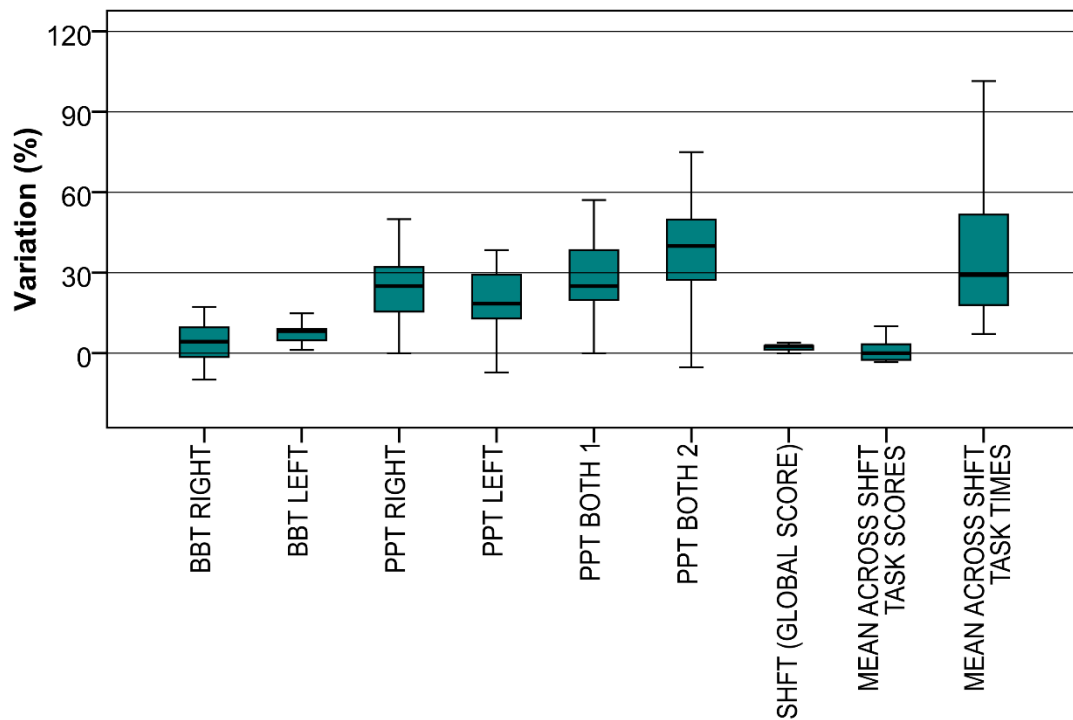
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Table 3: Mean (SD) time of accomplishment (in seconds) of each SHFT task and mean (SD) percentage of time increase. Significant differences after applying a repeated measures ANOVA were marked (\*) when  $sig. \leq 0.05$ , (\*\*) when  $sig. \leq 0.01$ .

ID	Task	Time of accomplishment without glove (sec)	Time of accomplishment with glove (sec)	Time increase (%)
1	Pick up coins from flat surface, put into a purse mounted on wall**	7.20 (1.69)	13.40 (8.14)	101.51 (163.75)
2	Open/close zip**	7.27 (1.74)	8.60 (1.96)	20.74 (23.55)
3	Pick up coins from purses**	14.50 (3.67)	23.70 (9.79)	69.54 (66.55)
4	Lift wooden cubes over edge 5cm in height**	4.13 (1.01)	4.90 (0.84)	23.47 (28.04)
5	Lift iron over edge 5cm in height**	3.43 (0.94)	3.93 (0.78)	20.67 (34.58)
6	Turning screw with screwdriver**	7.47 (1.85)	9.57 (2.46)	33.92 (41.48)
7	Pick up nuts and screw on bolts**	22.87 (6.36)	33.10 (12.91)	49.58 (53.12)
8	Put key into lock, turn 90 degrees**	4.87 (1.14)	7.27 (1.84)	53.28 (37.51)
9	Turn door-handle 30°*	2.73 (0.58)	3.07 (0.69)	15.28 (30.96)
10	Unscrew lid of jars**	6.80 (1.61)	8.27 (2.12)	24.41 (28.70)
11	Do up buttons**	15.13 (4.0)	22.50 (6.13)	53.94 (45.13)
12	Put on tubigrip stocking on the other hand**	8.03 (2.16)	12.67 (4.21)	65.54 (63.09)
13	Cut play dough with knife and fork	10.47 (3.42)	11.33 (3.00)	13.22 (26.68)
14	Write with a pen**	5.40 (1.10)	6.47 (1.31)	21.18 (17.90)
15	Fold sheet of paper and put into envelope**	16.63 (4.33)	22.33 (4.37)	40.42 (35.80)
16	Put a paper-clip on an envelope**	5.33 (1.32)	7.57 (1.99)	50.10 (52.14)
17	Lift telephone receiver, put to ear**	2.00 (0.37)	2.63 (0.81)	37.22 (53.19)
18	Pour water from carton**	19.83 (2.39)	21.23 (3.05)	7.19 (9.66)
19	Pour water from jug*	7.40 (2.14)	7.97 (1.90)	11.11 (23.53)
20	Pour water from cup	6.00 (1.51)	6.43 (1.30)	10.92 (24.42)

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156 Figure 3 shows an overview of the percentage of score reduction observed for BBT, PPT and  
 157 SHFT (Table 1), along with the mean percentage of reduction of scores of SHFT tasks (Table 2)  
 158 and the mean percentage of increase in time of accomplishment of SHFT tasks (Table 3).



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Figure 3: Changes in scores and mean time.

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#### 4. DISCUSSION

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In accordance with previous works (Bishu et al., 1993; Dianat et al., 2010; Johnson and Sleeper,

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1986; Muralidhar et al., 1999; Nelson and Mital, 1995; Torrens and Newman, 2000), the scores

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when using gloves showed a reduction in motor skills and manipulation capabilities at different

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levels of precision. This reduction has been previously reported to depend on certain glove

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characteristics like glove material and thickness (Banks, 1979; Bense, 1993; Muralidhar et al.,

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1999; Plummer et al., 1985). Furthermore, wearing a glove implies a change in frictional

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conditions which, depending on the glove's material, affects manipulation to different extents

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(Bronkema-Orr and Bishu, 1996; Westling and Johansson, 1984). With the CyberGlove model

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with 18 DoF, which has uncovered fingertips, the protective inner glove is worn (as indicated by

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the glove manufacturer), which reduces touch sensitivity. For this glove model, cutting the finger

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ends of the inner glove to uncover fingertips may help increase touch sensitivity and, therefore,

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dexterity.

174 Fine motor skills, evaluated through the PPT, are highly affected by the use of instrumented  
175 gloves, as shown by a reduction in the scores by 29% (mean reduction of the four parts of the  
176 test). The highest reductions were found in the parts of the PPT that required the use of both hands  
177 simultaneously, i.e. the ones involving the finest motor skills. The stronger effect on dexterity  
178 reported while performing precision tasks using both hands can be attributed to reduced  
179 somatosensory feedback in both hands simultaneously, which is highly related to touch of  
180 sensitivity which, in turn, diminishes while wearing gloves (Dianat et al., 2010). Such reduced  
181 feedback may affect manipulation (Hermsdörfer et al., 2004) and, therefore, dexterity.

182 Gross motor skills, assessed by means of the BBT, are less affected, with a decrease of about  
183 7.8%. The overall capability to perform ADL, when assessed through the standardised score of  
184 the SHFT, is only affected by a reduction of 2.7%. The difference in the individual scores for each  
185 task varies from a reduction of 16.67% to an increase of 10%, which is statistically significant  
186 only in the four tasks that involve the finest motor skills (picking up coins, screwing nuts,  
187 buttoning and unbuttoning, and folding paper and putting it into an envelope) where the score  
188 decreases.

189 However, the standardised score for the SHFT is quite rough, and especially the individual scores,  
190 which only consider a five-level score and the time of accomplishment of the tasks is considered  
191 in wide ranges (<20s, <40s, <60s, >60s). Furthermore, the grasp classification score may be  
192 somewhat subjective, as it depends on the operator. Nevertheless, when considering the exact  
193 times of accomplishment, increases from 7% to more than 100% were found, most of them  
194 statistically significant, even though no important reductions were found in the SHFT scores. The  
195 SHFT contemplates a large number of representative tasks and grasps (in comparison to BBT and  
196 PPT), but it was designed to evaluate patients with an important reduction in mobility (e.g. after  
197 an ictus). Hence despite its validity having been proved with patients with chronic stroke  
198 (Brogårdh et al., 2007) or burned hands (Weng et al., 2010) to measure hand function, it is not  
199 accurate enough to measure the effects of wearing gloves.

200 With regard to the effects on hand kinematics, the only information that can be extracted from  
201 BBT and PPT is that the decrease in scores reported implies a lower velocity of performance, and  
202 therefore lower hand joint velocity can be expected. The same occurs with the times of  
203 accomplishment reported in SHFT. Nevertheless, the stiffness of the glove may be affecting the  
204 range of motion and, consequently, hand kinematics. We can therefore observe that kinematic  
205 parameters (i.e. velocities and postures) may be affected when wearing instrumented gloves.  
206 Thus, data obtained using other motion capture systems that do not affect motor skills (e.g. optical  
207 systems) should not be compared with those obtained using instrumented gloves, in order to avoid  
208 bias.

209 A possible bias in studies that have used data gloves can be discussed from the results obtained  
210 herein depending on the recorded tasks and the reported parameters. Applications that have used  
211 the glove to record grasping static postures to validate other motion data systems (El-Sawah et  
212 al., 2007; Glauser et al., 2019) or simulation (Nogueira et al., 2019; Sancho-Bru et al., 2014)  
213 would not be affected by reported loss of dexterity, although the analysed postures may slightly  
214 differ from those used in bare-handed conditions (O'Hara, 1989). Similarly, applications that have  
215 recorded free movements for purposes such as identifying the intended type of grasp or movement  
216 performed (Naik et al., 2014; Schreck et al., 2018; Stival et al., 2019) would not be significantly  
217 affected by loss of dexterity, although glove stiffness may require slightly higher muscle activity  
218 to perform the movements. On the contrary, applications in high precision tasks, such as assessing  
219 manual dexterity in simulation-based surgery (Itkowitz et al., 2018; Lemos et al., 2017), would  
220 be clearly affected. Therefore, existing gloves should be improved for such purposes. In addition,  
221 the studies that have analysed joint velocities and/or accelerations (Jarque-Bou et al., 2018; Lin  
222 et al., 2019; Sarawate et al., 2015) may report lower velocities than real ones as the time required  
223 to perform a task would be longer than for doing it bare-handed. The joint velocity bias is expected  
224 to be higher for those tasks requiring more precision. Nevertheless, dexterity may also be affected  
225 when recording hand posture by other motion capture systems (e.g. markers of optical motion

226 capture systems that may collide during manipulation), and this effect has not yet been studied as  
227 far as the authors know.

228 Even though, despite all the advantages that instrumented gloves offer regarding other motion  
229 capture systems, it is not the most suitable motion capture system when performing tasks requiring  
230 fine motor skills (as the laparoscopy one in Sánchez-Margallo et al., 2014), but are appropriate  
231 for gross motor skills and activities of daily living (as in Gracia-Ibáñez et al., 2017). However,  
232 users should take into account that kinematic parameters such as velocities should not be  
233 compared with those obtained using other systems.

## 234 **5. CONCLUSIONS**

235 The use of instrumented gloves to record hand kinematics is only recommended when performing  
236 tasks requiring medium and gross motor skills. Care has to be taken when comparing velocities  
237 with those obtained using other systems.

## 238 **CONFLICT OF INTEREST STATEMENT**

239 The authors declare no conflict of interest for publishing this work.

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